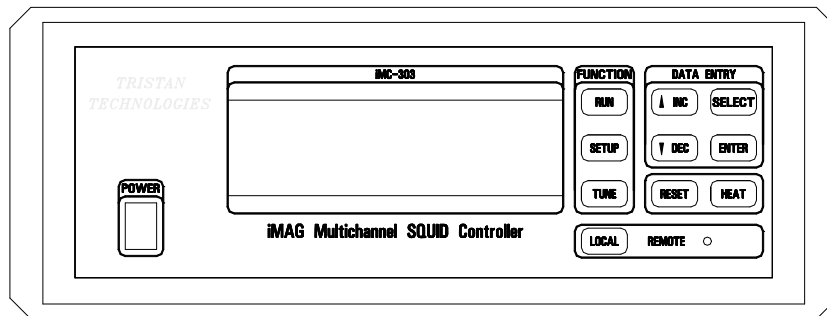


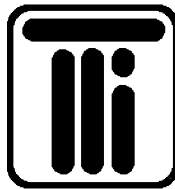
User's Manual

for

iMAG HTS Multi-Channel dc SQUID System



By:



Tristan Technologies, Inc.

San Diego, California

USA

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WARRANTY

TRISTAN TECHNOLOGIES Limited Warranty

TRISTAN TECHNOLOGIES Inc. warrants this product for a period of twelve (12) months from date of original shipment to the customer. Any part found to be defective in material or workmanship during the warranty period will be repaired or replaced without charge to the owner. Prior to returning the instrument for repair, authorization must be obtained from TRISTAN TECHNOLOGIES, Inc. or an authorized TRISTAN TECHNOLOGIES service agent. All repairs will be warranted for only the unexpired portion of the original warranty, plus the time between receipt of the instrument at TRISTAN and its return to the owner.

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SAFETY PRECAUTIONS

Refer to this section before you install or operate the system.

Refer to the manuals for the supplied computer and monitor before you install or operate the system.

The instrument chassis must be connected to an electrical ground. The three contact power cord supplied with the instrument provides a connection to the power source and a protective ground. The protective ground contact is connected to the instrument chassis. Use a power source outlet which has a properly grounded protective-ground contact to minimize a shock hazard.

Do not remove product covers or panels or operate without all covers and panels in place.

Do not attempt to repair, adjust, or modify the instrument, as this could void the product warranty. For service, return the instrument to Tristan Technologies, Inc. or any authorized representative.

Do not operate this instrument in a volatile environment, such as in the presence of any flammable gases or fumes.



REGULATORY INFORMATION

- This apparatus has been tested to the requirements of the EMC Directive 89/336/EEC and the Low-Voltage Directive 73/23/EEC.
- This apparatus meets the requirements as ISM Group 1, Class A equipment per EN 5011:1991 (Industrial and Light Industrial Environment).

SYMBOLS

The following symbols may appear on the equipment.






Symbol	Definition
	Use caution when you work around hardware that contains this symbol. Refer to the manual whenever you see this symbol; the manual explains the safety procedures that you follow.
	Use caution when you work around hardware that contains this symbol. This symbol indicates that the hardware may cause electric shock or burns. Refer to the manual whenever you see this symbol; the manual explains the safety procedures that you follow.
	Use caution when you work around hardware that contains this symbol. This symbol indicates incoming alternating current; this symbol is used in conjunction with the exclamation-point symbol.
	Use caution when you work around hardware that contains this symbol. This symbol indicates the system's main safety ground. Refer to the maintenance manual whenever you see this symbol; the maintenance manual explains the safety procedures that you follow.
	Use caution when you work around hardware that contains this symbol. This symbol indicates potentially unstable open drawers. Refer to the manual whenever you see this symbol; the manual explains the safety procedures that you follow.

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Chapter 1

Introduction

Congratulations!

You are now the owner of an iMAG Series SQUID System . The iMAG Series is a family of advanced superconducting magnetic sensing components made by Tristan Technologies. iMAG products are designed to allow you to make use of the unique performance advantages inherent in superconducting quantum interference devices with a new generation of high-performance sensors based on revolutionary "high-temperature superconductor" technology. The high-temperature iMAG SQUID sensor provides magnetometer performance at 77 K that is commercially available nowhere else and that is competitive with any device reported in research laboratories.

Your high-temperature or low-temperature iMAG System also includes high-performance SQUID control electronics. The iMC-303 Multichannel SQUID Controller is a microprocessor controlled instrument that provides advanced operation and control functions for up to three SQUID sensors and provides digital and analog outputs via standard interfaces. The iMC-303 mates to a companion iFL-301 flux-locked loop for each sensor channel via a copper and fiber optic interconnect. The flux-locked loop is an extremely compact module designed to be installed near the cryogenic sensor head; multiple loops can be bolted together to minimize the space that they occupy.

This user's guide contains the information you need to install, configure and operate the iMAG components that comprise the system you ordered. It includes check-out procedures and other useful information.

The iMAG Series of SQUID electronics is an innovative product that provides capabilities that, in some cases, are not available elsewhere. We at Tristan stand behind this product and are anxious to help you utilize it to its fullest potential. We ask that you take the time to study this user's guide in detail before attempting to use the system.

Once again, thank you for becoming an iMAG customer.

1. Introduction to the iMAG Multichannel System

What is iMAG?

The 77 K System:

The 77 K system is the first high-performance HTS dc SQUID system available on the commercial market. Due to the unique characteristics associated with the materials used to fabricate HTS devices, it is not currently possible to supply HTS SQUID systems with input terminals. There is not at present a known way to directly connect an external superconducting circuit to an HTS SQUID. Therefore, all HTS iMAG systems come with an integral input coil attached to the SQUID, thereby creating an integrated magnetometer. For this reason, all signals must be inductively coupled to an HTS iMAG system.

For applications where one is only interested in detecting magnetic fields, simply observe the SQUID output to monitor the magnetic field at the input. HTS iMAG systems have a typical field resolution of better than 100 femtotesla ($1 \text{ fT} = 10^{-15} \text{ T}$) from a few Hz to 20 kHz. In order to measure something other than magnetic field at the location of the SQUID sensor, it is necessary to build your own input circuit and inductively couple it to the SQUID. Tristan can optionally supply integral gradiometer pickup coils and other input circuits and we invite your inquiries for circuits to meet your specific needs.

Control Electronics Description:

The iMAG system is based upon a high-performance multichannel controller designed for use with SQUID (Superconducting Quantum Interference Device) sensors. The system has a wide range of features which allow high sensitivity and low-noise operation. Flexible channel configurations make it possible to control SQUID sensors operating at 77K or 4 K.

The iMAG System standard features include:

- **Three, Configurable SQUID Channels**
The iMC-303 Multichannel SQUID Controller allows simultaneous control of up to 3 SQUID channels. Each channel may be independently configured for operation with 77 or 4 Kelvin SQUID sensors.
- **Compact Remote Electronics**
The iFL-301 Flux-Locked Loop contains advanced hardware designs for signal amplification and conditioning in a compact package.
- **Flexible**
Connections from the iFL-301 Flux-Locked Loop to the SQUID sensor are provided via flexible, shielded cable, permitting numerous sensor positioning options.
- **Digital Control**
The iMC-303 Multichannel SQUID Controller is based on a 32-bit microprocessor

operating at 16 MHz to implement advanced signal processing techniques, control, and data acquisition.

- **Auxiliary Channel**

An Auxiliary Channel provides a means for processing an external signal and synchronizing it with the data from the SQUID channels. This can be used with a cryogenic level meter, or for acquiring data from external sources

- **Accurate**

Use of a 16-bit, dual-channel Analog-to-Digital converter ensures accuracy and high speed. The converter inputs are multiplexed to accommodate the 3 SQUID channels and the Auxiliary Channel.

- **Fiber Optic**

The iMAG composite cable uses optical fiber communication to the iFL-301 Flux-Locked Loop to eliminate grounding and shielding problems that often affect SQUID electronics.

- **Autotuning**

An Autotune function determines optimum SQUID operating parameters with the touch of a single key on the front panel.

- **Remote Control**

The iMC-303 Multichannel SQUID Controller is designed for incorporation in automated systems using either IEEE-488 or RS-232 interface ports, and both are provided as standard features. Full computer control of all front panel functions is provided.

- **High Speed Data Acquisition**

The iMC-303 Multichannel SQUID Controller provides high speed data collection/acquisition for all SQUID channels via the IEEE-488 interface port. Configurable data acquisition rates up to 20,000 words per second are supported.

- **Master/Slave Configuration**

Multiple iMC-303 Multichannel SQUID Controller units can be configured to operate systems consisting of more than 3 SQUID sensors. A clock input and output are provided on each unit so that a master clock can be used to drive all Flux-Locked Loops in the system..

1.1. iMAG System Configuration

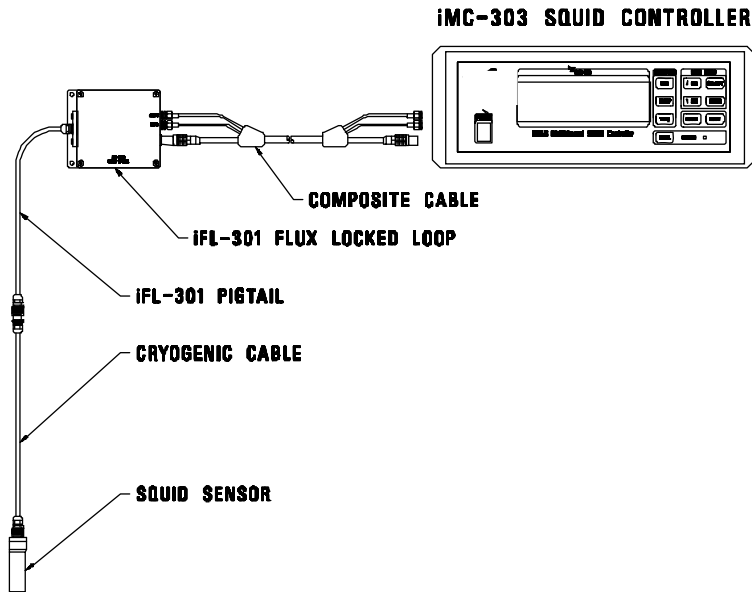


Figure 1 iMAG System Configuration

Chapter 2

Installation and Setup

2. Installation and Setup

2.1. Unpacking And Inspection

Prior to unpacking the iMAG system, you should check the carton for any shipping damage. If damage is observed, notify the carrier immediately to allow for a possible insurance claim.

The following items are included with the standard iMAG system. If any items are missing, notify your TRISTAN representative immediately.

2.1.1. Packing List:

- 1 iMC-303 Multichannel SQUID Controller
- 1 to 3 iFL-301 Flux-Locked Loop Module(s)
- 1 to 3 SQUID Sensor(s)
- 1 to 3 Flexible Model SP Cryogenic Cable(s)
- 1 to 3 Fiber Optic Composite Cable(s), 6 meters each
- 1 to 3 System Integration Test Report(s)
- 1 to 3 SQUID Test Report(s)
- 1 iMAG dewar
- 1 Mu-metal SQUID Shield and one Shield collar (optional)
- one HTS iMAG Multi-Channel SQUID System User's Manual
- fuse installed in the Controller Power Entry Module
- AC Power Cord

2.2. Power Requirements

All system power is supplied to the SQUID Controller. The iMC-303 Multichannel SQUID Controller is configured to support ac voltages of 100, 120, 220, 240 Volts at either 50 or 60 Hz.. These voltage selections are enabled by rotating the jumper block in the fuse drawer on the back of the unit to display the desired operating voltage in the window. Tolerance on voltages is $\pm 10\%$.

WARNING:

Never attempt to operate the iMC-303 Multichannel SQUID Controller at a different input line voltage than is shown on the power input module on the rear panel. Serious injury or damage may result

2.2.1. Instrument Fusing

A user-replaceable fuse is mounted in the AC power entry module. This module also includes a spare.

The iMC-303 Multichannel SQUID Controller requires a 3 Amp slow blow fuse for 110 and 120 V_{AC} configurations and a 1.5 Amp slow blow fuse for 220 and 240 V_{AC} configurations.

WARNING:

Always replace the fuse with the correct value to prevent shock and fire hazards, as well as damage to the iMC-303 Multichannel SQUID Controller.

2.2.2. Grounding And Shielding

The Ground wire on the AC line cord must be connected to a safety ground that does not normally carry electrical current. This safety ground becomes the Chassis Ground of the instrument and is used as the ground point for all cable shields. Thus, it is important to ensure a good quality connection. The iMC-303 Multichannel SQUID Controller comes equipped with a three-conductor power cord that connects the instrument chassis to earth ground.

WARNING: TO PREVENT SHOCK AND FIRE HAZARDS, ALWAYS CONNECT THE POWER CORD TO A THREE-CONDUCTOR, GROUNDED RECEPTACLE.

2.3. Operating Environment

2.3.1. Operating Temperature Range

The iMC-303 Multichannel SQUID Controller is designed to operate over an ambient temperature range of 25 °C ± 5 °C.

2.3.2. Humidity/Altitude

A normal laboratory environment is expected. Proper operation over extremes of altitude or humidity is not guaranteed.

WARNING:

To prevent shock and fire hazards, as well as damage to the iMC-303 Multichannel SQUID Controller, it should not be allowed to get wet or operate in a condensing atmosphere.

2.4. Rear Panel Layout

The rear panel layout of the iMC-303 Multichannel SQUID Controller is illustrated in the following diagram:

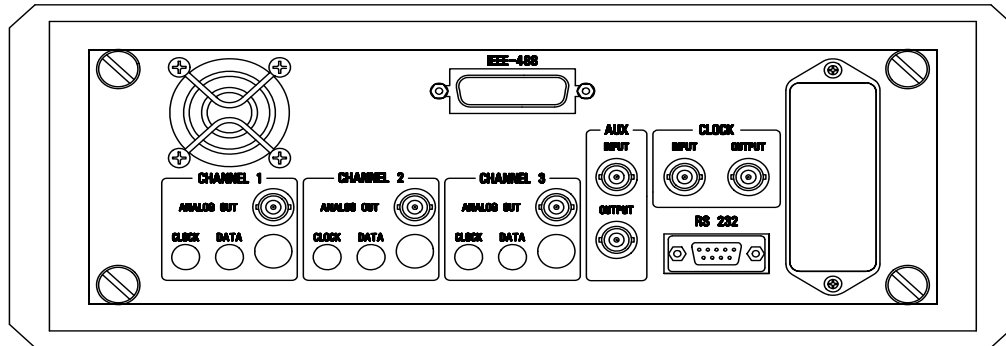


Figure 2 iMC-303 Multichannel SQUID Controller Rear Panel

2.5. System Interconnects

2.5.1. Composite Cable Connection

The Tristan model CC-6 Composite Cable is used to transmit power and high-speed control signals to the iFL-301 Flux-Locked Loop, and to transfer analog signals to the iMC-303 Multichannel SQUID Controller. This cable contains a composite of shielded conductors and fiber optics.

Attach the 5-pin LEMO cable connectors to the iMC-303 Multichannel SQUID Controller Channel 1, 2, or 3 mating LEMO connector on the rear panel, and to the mating LEMO connector on the corresponding Flux-Locked Loop. To do this, simply align the red dots on the mating connectors, and push until it “clicks” in place. To remove, pull back on the knurled portion of the cable connector. Do not twist the LEMO connector.

Remove the protective covers from the ends of the fiber optic cables labeled “Clock” and “Data”. Insert the cables into the iMC-303 Multichannel SQUID Controller rear panel and iFL-301 Flux-Locked Loop fiber optic connectors labeled “Clock” and “Data”. Carefully thread the connectors to avoid cross threading, then tighten snugly to assure that a good connection has been made. Use caution when handling the fiber optic cables. The ends have been highly polished, and any surface abrasion or severe bending of the cables may cause an unrecoverable degradation in performance.

CAUTION: USE CAUTION WHEN HANDLING AND ROUTING THE FIBER OPTIC CABLES. ANY SURFACE ABRASION OR SEVERE BENDING MAY CAUSE AN UNRECOVERABLE DEGRADATION IN PERFORMANCE.

2.5.2. Cryogenic Cable Connection

The Model SP Cryogenic Cable is the link between the SQUID Sensor immersed in a cryogen and the iFL-301 Flux-Locked Loop at room temperature. This is a flexible cable comprised of 5 shielded, twisted pair transmission wires encased in a Teflon-coated outer shield. The inner and outer shields are constructed from 60% coverage braided phosphor-bronze wire, which provide excellent rejection of electro-magnetic interference.

To connect the Model SP Cryogenic Cable to the iFL-301, align the red dot on the LEMO connector at the end of the iFL-301 Pigtail with the red dot on the connector at the mating end of the Model SP Cryogenic Cable. Push gently until it “clicks” in place. To remove, pull back on the knurled portion of the cable connector. Do not twist the LEMO connectors.

To connect the Model SP Cryogenic Cable to the iMAG SQUID sensor, align the red dot on the LEMO iMAG SQUID sensor connector with the mating end of the Model SP Cryogenic Cable. Push gently until it “clicks” in place. To remove, pull back on the knurled portion of the cable connector. Do not twist the LEMO connectors.

2.5.3. Remote Interface Connection

Connection to the IEEE-488 is via an IEEE-488 connector on the rear panel.

Connection to the RS-232 is via a DB-9 connector on the rear panel.

The enabling of the desired interface is done via menu selection on the front panel.

2.5.4. Auxiliary Channel Connections

The auxiliary input is provided for signal conditioning and digitizing of a user supplied signal. This input has the same signal conditioning options as the 3 SQUID channels.

The user may monitor this channel via the analog output on the back panel or the remote interfaces.

2.5.5. Clock Connections

The CLOCK Input and Output BNC's make it possible for several iMC-303 Multichannel SQUID Controllers to be interconnected for operation of systems consisting of more than three SQUIDS. In this configuration, one iMC-303 Multichannel SQUID Controller is designated “MASTER” via menu selection, and its “CLOCK Output” is connected to subsequent controllers’ “CLOCK Input”. The clock signal is then daisy chained from “CLOCK Output” to “CLOCK Input” of remaining Controllers. These remaining iMC-303 Multichannel SQUID Controllers are designated “SLAVE” via menu selection. In this manner, the “MASTER” iMC-303 Multichannel SQUID Controller provides a common clock for all iFL-301 Flux-Locked Loops. Use of this common clock eliminates the need for multiple clocks to drive the SQUIDS, ensuring that harmonics are not generated in multiple SQUID configurations.

Each iMC-303 Multichannel SQUID Controller is then controlled individually through the front panel or computer interface to change operating parameters and acquire data.

2.6. Mounting The iMC-303 Multichannel SQUID Controller

2.6.1. Bench mounting

The iMC-303 Multichannel SQUID Controller comes supplied ready for bench use. Rubber feet covers are supplied on the bottom of the instrument, which can easily be removed. The front of the instrument may be elevated by removing the rubber covers, inserting a small, straight-blade screwdriver into the large gray tabs on the bottom cover, and prying up. Slide these tabs into the small gray feet and replace the rubber covers.

In order to stack more than one iMC-303 Multichannel SQUID Controller, first remove the rubber feet covers and retract the large gray tabs into their original positions. Then, simply place one controller on top of the other and slide the feet into the alignment slots on the top of the instrument you wish to stack.

2.6.2. Rack Mounting

An optional rack mount kit for a standard 19-inch rack is available for the iMC-303 Multichannel SQUID Controller.

Chapter 3

iMC-303 Multichannel SQUID Controller Operation

3. iMC-303 Multichannel SQUID Controller Operation

3.1. Keypad Summary

The response of the iMC-303 Multichannel SQUID Controller to its various keys is summarized in the following sections. The “FUNCTION” keys change the iMC-303 Multichannel SQUID Controller operating Mode and the menu displayed on the screen. The “DATA ENTRY” keys change the settings within each menu. The “LOCAL” key allows access to the front panel keys while the unit is interfaced with a remote computer. Once a setting has been changed it is stored in non-volatile memory. When the instrument power is cycled, the most recent setup and operating parameters are retained.

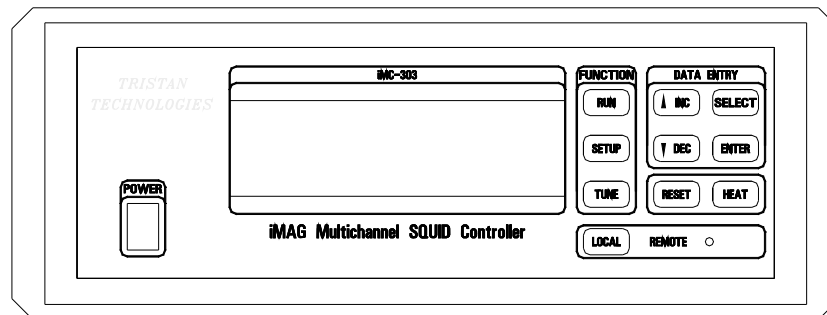


Figure 3 iMC-303 Multichannel SQUID Controller Front Panel

3.2. FUNCTION Keys

3.2.1. RUN Key

Pressing the RUN key causes the iMC-303 Multichannel SQUID Controller to enter the RUN mode and show the normal operating display. The iMAG Controller will begin (or continue) controlling the SQUID sensors immediately using the parameters shown on the RUN menu display and from the most recent TUNE cycle.

3.2.2. SETUP Key

Pressing the SETUP key displays the main SETUP menu used to change the iMC-303 Multichannel SQUID Controller operating parameters. The iMAG Controller will continue to operate the SQUID sensor until a parameter is changed which will directly effect SQUID control.

3.2.3. TUNE Key

The TUNE Key causes the iMC-303 Multichannel SQUID Controller to determine the optimum SQUID TUNE parameters for each installed channel, and show the result in the AUTOTUNE Display. The AUTOTUNE algorithm is executed regardless of the menu currently displayed, and is a fully automatic feature.

3.2.4. DATA ENTRY Keys

The DATA ENTRY keys change the settings within each menu. Entering data from the front panel is a straightforward process using the following keys:

3.2.5. SELECT Keys

The SELECT key moves the cursor (indicated by flashing text) around the display, allowing the selected text to be changed. Each time the SELECT key is pressed, the cursor moves to the next position.

3.2.6. INC (increment) and DEC (decrement) Keys

The two keys labeled INC and DEC are used to scroll through the possible choices for a given item that has been selected using the SELECT Key. For some fields (like the BIAS and MODULATION selections in the MANUAL TUNE display), it will increment or decrement numeric values for user selection. Holding the INC and DEC keys will increment/decrement the values more quickly. These keys will also navigate through the selections in the SETUP menu.

3.2.7. ENTER

The ENTER key is used in the SETUP menu to choose which submenu to enter. For instance, to enter the MANUAL TUNE display, press SETUP, press SELECT or INC/DEC until the cursor is on MANUAL TUNE, then press ENTER. The MANUAL TUNE display will appear on the front panel.

Pressing ENTER from the RUN screen will toggle between the RUN menu and the barchart view of the RUN menu.

Pressing ENTER from the Channel field of the MANUAL TUNE menu will transition the instrument to the RUN mode while remaining in the MANUAL TUNE menu. This enables the user to adjust the TUNE parameters while the Flux-Locked Loop is in the locked mode. Pressing ENTER from any other menu has no effect on the state of the instrument.

3.3. LOCAL Key

Pressing the LOCAL key unconditionally terminates remote control of the iMC-303 Multichannel SQUID Controller via either the RS-232 or IEEE-488 port and turns off the REMOTE indicator LED. This permits manual control via the front panel keys. All keys other than the LOCAL key are disabled if the REMOTE indicator LED is on. Remote operation of the iMC-303 Multichannel SQUID Controller will return with the next command received on a remote interface.

3.4. RESET Key

This key resets the operating point of the SQUID sensors to an output level closest to 0 volts dc.

3.5. HEAT Key

Regardless of the menu displayed, pressing the HEAT key heats the SQUID sensor on all installed channels for a user selected period of time, and then finds new operating parameters using the AUTOTUNE algorithm.

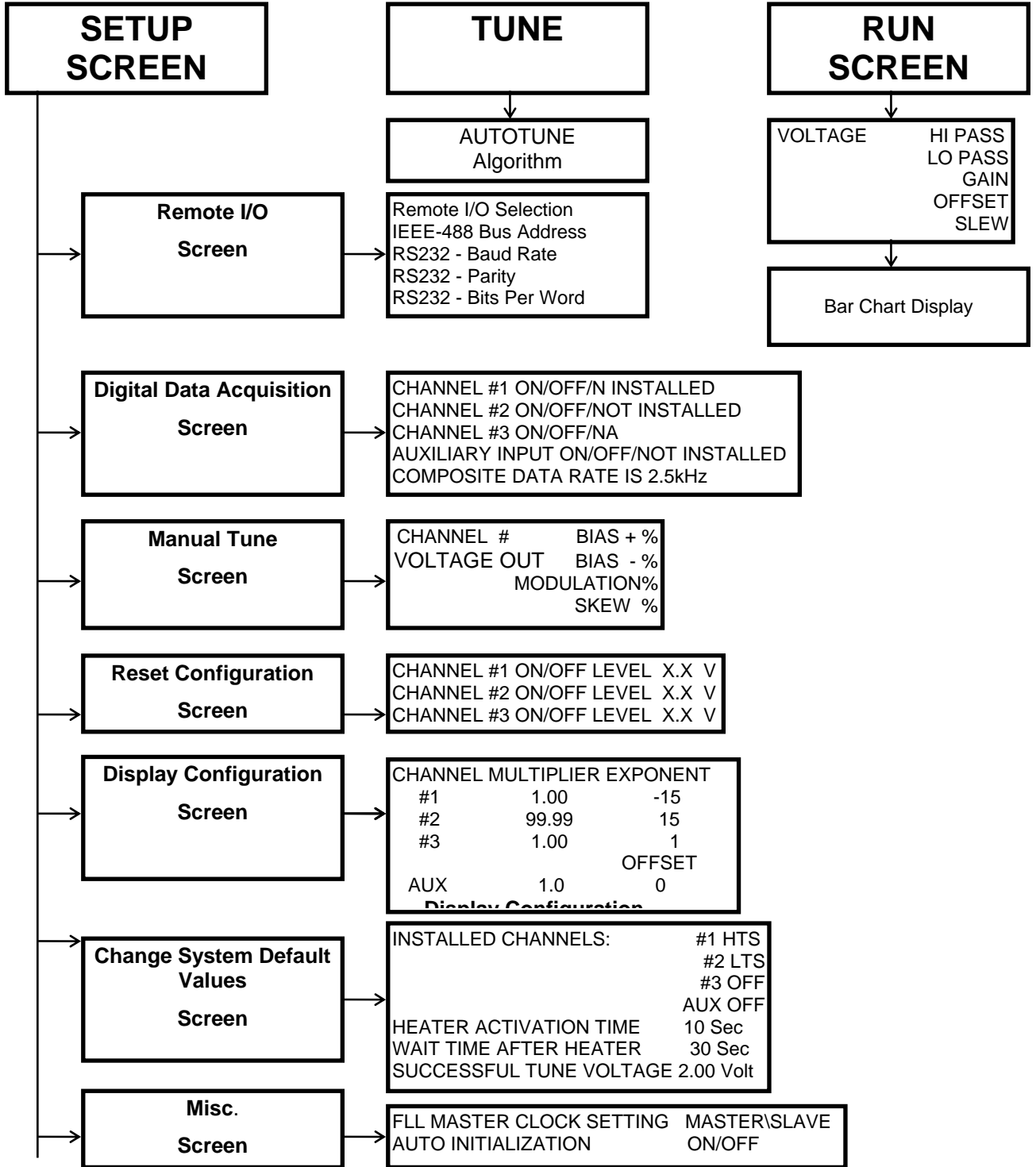
3.6. Special Key Assignments

While in the MANUAL TUNE menu with the cursor in the channel field, pressing the ENTER key will place the system in RUN mode while remaining in the MANUAL TUNE screen. The user may then manually adjust the tune parameters while the system remains in RUN mode.

3.7. Menu Tree

iMC-303 functions are represented by the following menus. Details of each operation are discussed in the next section.

FUNCTION KEYS: **SETUP**



3.8. OPERATING MODES AND MENU DESCRIPTIONS

The iMC-303 Multichannel SQUID Controller has three distinct modes of operation: the RUN, SETUP, and TUNE modes. These are accessed using the buttons in the FUNCTION section of the front panel or via the remote interface. If the iMC-303 Multichannel SQUID Controller is in the LOCAL condition (REMOTE indicator LED turned off), pressing any of these buttons will immediately place the iMAG into the indicated operating mode, regardless of its current status.

3.8.1. RUN

RUN mode is entered by pressing the RUN button on the front panel. The following screen will be displayed.

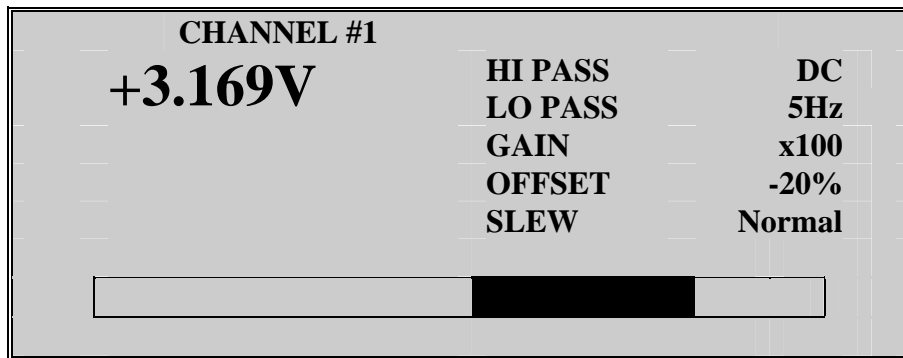


Figure 4 Run Menu

3.8.1.1. CHANNEL

Once the cursor has been moved to the CHANNEL position, the displayed channel can be scrolled using the INC and DEC keys. The operating parameters may be changed for each installed channel. If the displayed channel has not been installed, “Channel Disabled” will appear on the screen. Note that when changing the AUX CHANNEL settings in the RUN display, the SLEW and OFFSET are disabled. These are SQUID Sensor parameters and are not available with the AUX CHANNEL.

3.8.1.2. HIGH PASS FILTER

The HIGH PASS FILTER is a single pole filter that is applied to the input signal from the SQUID sensor prior to amplification. This filter resides in the iMC-303 Multichannel SQUID Controller. It can be set for dc (no filtering), or 0.3 Hz (equivalent to the ac coupling feature found on some instruments) which has a corner frequency of 0.3 Hz.

3.8.1.3. LOW PASS FILTER

Each channel may be filtered by choosing one of three, four-pole Butterworth filters. The LOW PASS FILTER settings are: OFF, 5 Hz, 500 Hz, and 5 kHz. By selecting OFF, the Analog Output bandwidth is limited by the iFL-301 Flux-Locked Loop to 20 kHz.

3.8.1.4. GAIN

The GAIN setting represents the gain applied to the signal prior to the LOW PASS FILTER and the Analog Output. This voltage output is a direct conversion of the flux in the SQUID sensor. For instance, a gain of x5 will yield 5 times the voltage (measured at the Analog Output) as a gain of x1 will, for the same amount of applied flux at the SQUID sensor.

There are nine possible GAIN selections in this menu: x1, x2, x5, x10, x20, x50, x100, x200, and x500. The overall gain is a combination of gains in the iMC-303 Multichannel SQUID Controller (out of loop gain) and in the iFL-301 Flux-Locked Loop (in loop gain). For GAIN selections x1, x2, x5, x10, x20, and x50 the in loop gain is unity. For GAIN selections x100, x200, and x500 the in loop gain is set at x100. The range of the Feedback Loop also changes as a function of the selected GAIN. The output can track $\pm 500 \Phi_O$ (1000 Φ_O peak-to-peak) in x1, x2, x5, x10, x20, x50 selections and $\pm 5 \Phi_O$ (10 Φ_O peak-to-peak) in the x100, x200, and x500 GAIN selections.

3.8.1.5. OFFSET

The OFFSET feature allows the user to inject a dc offset current into the Modulation coil to effectively null the dc output of the SQUID sensor. This gives the iMC-303 Multichannel SQUID Controller maximum dynamic range and allows the gain setting to be increased to obtain maximum sensitivity. The OFFSET range on the display is -100% - +100%. This corresponds to $\pm 1.5 \Phi_O$ at the SQUID in the $\pm 500 \Phi_O$ range, and is independent of the GAIN setting. Low frequency noise will be injected by settings other than -100%.

3.8.1.6. SLEW RATE

There are two SLEW selections (operating bandwidths), NORMAL (20 kHz) and SLOW(200Hz), which allow the user to optimize feedback loop performance using the SQUID Sensor. Both NORMAL and SLOW are available when using the GAIN settings of x100 - x500. Only the NORMAL selection is available when using the GAIN settings of x1 - x50. The SLEW is set by default to NORMAL.

When selecting an SLEW setting, the user should configure the instrument to track the signals from the SQUID Sensor. rf transients may cause the Feedback Loop to be unable to track the desired signal. The NORMAL mode is generally less susceptible to rf transients, and the SLOW mode is less effected by magnetic transients.

3.8.1.7. Output Voltage

The large characters in the display directly below the CHANNEL field display the SQUID Output Voltage. This voltage corresponds to the amount of magnetic flux at the SQUID sensor (V/Φ_O). The voltage is a function of the GAIN setting, the higher the GAIN, the higher the resultant output voltage. The Output Voltage display is a digital representation of the level on the Analog Output BNC found on the rear panel. The range for this output is ± 4.5 volts.

3.8.1.8. Barchart

The barchart at the bottom of the RUN screen is a graphical representation of the Output Voltage field and has a range of ± 4.5 Volts.

3.8.1.9. Multi-channel Barchart Display

When the cursor is in the CHANNEL field of the RUN menu, pressing ENTER results in a multi-channel display. This multi-channel display shows the numerical value of the selected channel, and a graphical representation of the value of all 4 channels in barchart form. The full scale corresponds to -4.5V to +4.5V.

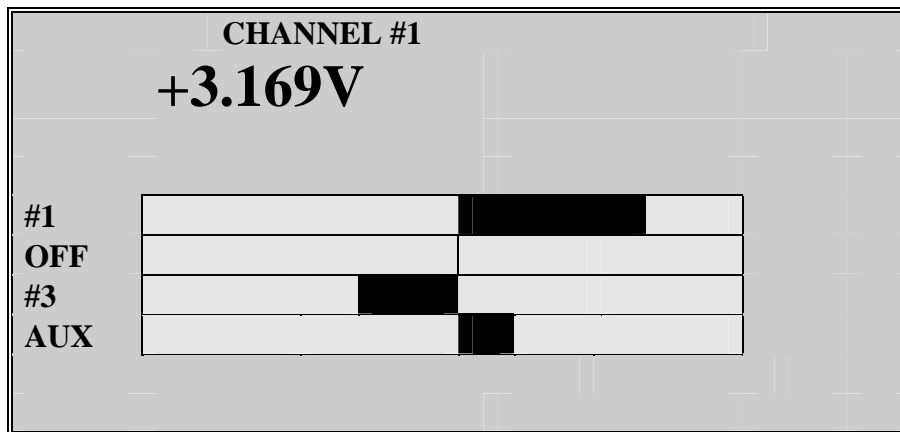


Figure 5 Multi-channel Barchart Screen

3.8.2. SETUP

The SETUP menu allows the user to enter the appropriate menu to manually change any of the desired operating parameters of the iMC-303 Multichannel SQUID Controller. The selections under the SETUP menu are: REMOTE I/O, DIGITAL DATA ACQUISITION, MANUAL TUNE, RESET CONFIGURATION, DISPLAY CONFIGURATION, CHANGE SYSTEM DEFAULT, and MISC.

The SELECT key, and the INC and DEC keys, are used to navigate through the selections. The ENTER key brings up the menu for the selection highlighted by the cursor.

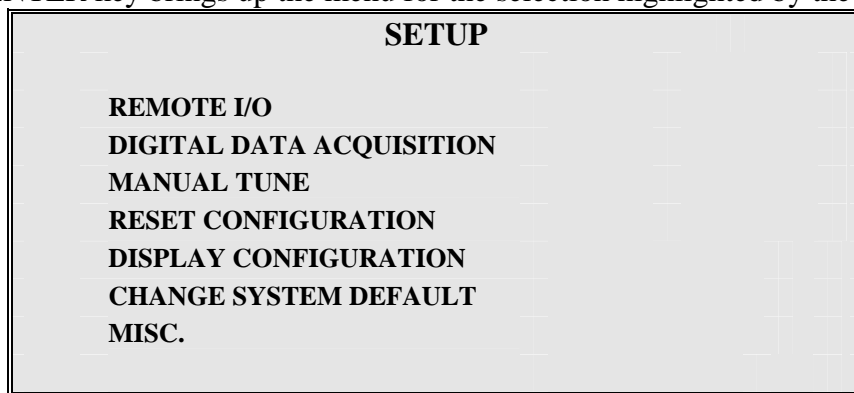


Figure 6 Setup Menu

3.8.2.1. REMOTE I/O

Select the REMOTE I/O menu from the SETUP Menu to change the remote I/O configuration. Details on Remote commands are described in Appendix A.

REMOTE I/O	
Remote I/O Selection:	RS232
IEEE-488 Bus Address:	15
RS232 - Baud Rate:	38400
RS232 - Parity:	OFF
RS232 - Bits Per Word:	8

Figure 7 Remote I/O Menu

The iMAG comes configured with IEEE-488 as the default setting. Use the SELECT and the INC or DEC keys to change the setting. Please note that only one of the interface connections can be activated at a time. Enter any desired IEEE-488 address between 1-31 (inclusive) using the INC or DEC keys. iMAG supports RS-232 baud rates between 300 and 38,400. The Parity is set to None and Bits per Word as 8 and may not be changed by the user. Once a selection has been made, it will be entered into non-volatile memory upon exit of the REMOTE I/O menu.

3.8.2.2. DIGITAL DATA ACQUISITION

DIGITAL DATA ACQUISITION		
CHANNEL #1	ON	
CHANNEL #2	NOT	INSTALLED
CHANNEL #3	ON	
AUXILIARY INPUT	OFF	
COMPOSITE DATA RATE IS	2.5 kHz	

Figure 8 Digital Data Acquisition Screen

The DIGITAL DATA ACQUISITION screen displays the current status of data acquisition. This is a status screen only, data acquisition parameters may only be set over the IEEE-488 interface. The channel status is ON, OFF and NOT INSTALLED. The data acquisition rate per channel is displayed on the lower portion of the display. See Appendix A under SDACQ command and Appendix C High Speed Data Acquisition for details.

The iMC-303 Multichannel SQUID Controller is capable of Data Acquisition rates of 20 kHz for one channel. Data Acquisition is limited to IEEE-488 interface only due to the inherent data transfer rate requirement. The Data Acquisition rates are shown below for the different channel configurations.

Channels	Speed
1	2.5K, 5K, 10K, 20K
2	2.5K, 5K, 10K, 20K
3	2.5K, 5K, 10K, 20K
AUX	2.5K, 5K, 10K, 20K
1,3	2.5K, 5K, 10K
2,AUX	2.5K, 5K, 10K
1,2,3,AUX	2.5K, 5K
1,2	2.5K, 5K
1,AUX	2.5K, 5K
2,3	2.5K, 5K
3,AUX	2.5K, 5K

Table 1 Data Acquisition Rates vs. Channel Configuration

3.8.2.3. MANUAL TUNE

The optimum SQUID TUNE parameters may be found manually via the MANUAL TUNE menu.

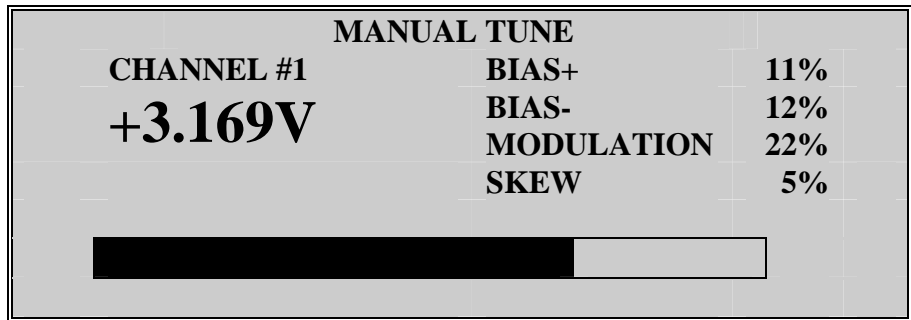


Figure 9 Manual Tune Menu

The MANUAL TUNE menu allows the user to change: the CHANNEL #, BIAS+, BIAS-, MODULATION, and SKEW values. Each of these values are displayed as a percent of full scale, 0-100%. The bar graph display and the large Voltage readout correspond to the peak RMS value of the SQUID V/Φ characteristic. Full scale for these measurements is 0 ± 4.5 volts dc. Measuring the V/Φ characteristic is a quantifiable means of determining optimum SQUID TUNE parameters.

3.8.2.3.1. BIAS+, BIAS-

The BIAS level is the actual amount of current applied to the SQUID sensor. By increasing the amount of BIAS, the current is increased across the superconducting Josephson junctions until a voltage is sensed by the iMC-303 Multichannel SQUID Controller. This is the point called the critical current (or I_c) where the junctions can no longer support resistanceless current flow. It is in a narrow region above the I_c that the optimum parameters for operating a SQUID are obtained. One of the sources of noise in HTS SQUID sensors is due to the fluctuations in the critical currents of the Josephson junctions. The iMAG System

implements a scheme to bias the SQUID first with one polarity and then in the opposite polarity in order to sample both sides of the current-voltage characteristic curve (ac Bias), thus eliminating critical current fluctuation contributions to the SQUID noise. This results in a significant reduction of low-frequency noise.

The BIAS+ is the value of the current when the SQUID is forward biased, and the BIAS- is the value of the current when the SQUID is reverse biased. These can be adjusted independently, and range from 0-100%. The bar graph display and the Voltage readout on the screen will accurately show the SQUID's response to changes in the BIAS level. As BIAS is incremented (from 0%), the voltage displayed will slowly increase, reach a peak and then begin to decrease. It is at this peak that the SQUID performance is usually at its best. It is possible to observe more peaks in the SQUID response as BIAS is incremented further. The peak which produces optimum performance can vary with different types of SQUID sensors. Refer to Section 6.1 for techniques on determining MANUAL TUNE parameters.

3.8.2.3.2. MODULATION

MODULATION is the amount of current fed to a small discrete coil directly on top of the SQUID. This current creates a small magnetic field, which is sensed by the SQUID sensor and causes it to exhibit very periodic behavior that looks much like a sine curve. The periodic nature of the SQUID allows it to be used as a very sensitive magnetic detector. These periods are expressed in terms of Φ_0 or Flux Quanta. As the MODULATION level is incremented, the voltage level and bar graph displayed will slowly increase, reach a peak, and then begin to decrease. Up to five peaks in the voltage out will be seen as the MODULATION is incremented from 0% to 100%. The first peak (that with the lowest MODULATION % level) typically provides optimum SQUID performance.

3.8.2.3.3. SKEW

The SKEW selection applies a correction to the relative timing of the flux modulation and bias reversal when using ac bias. Once the BIAS+ (forward bias) and the BIAS- (reverse bias) and MODULATION are adjusted, the SKEW can be set. The full scale range for SKEW is also 0-100%.

3.8.2.4. RESET CONFIGURATION

The AUTORESET menu displays the status (ON or OFF), and the RESET LEVEL in volts for channels 1-3.

AUTORESET			
CHANNEL #1	ON	LEVEL	1.5 V
CHANNEL #2	OFF	LEVEL	1.5 V
CHANNEL #3	ON	LEVEL	0.00 V

Figure 10 Reset Configuration Menu

If ON is selected for any of the channels, A SQUID RESET may be automatically triggered in one of two ways: by the output voltage level exceeding the LEVEL value set in the AUTORESET menu, or by an input signal exceeding ± 3 V when the HIGH PASS FILTER is engaged.

The digitized channel output voltage is continuously monitored by software and if the signal level exceeds the range set by the user in the LEVEL field of the AUTORESET menu, an automatic RESET is triggered. Note that the setting of this \pm voltage level parameter is dependent on the GAIN setting chosen in the RUN display. If this voltage value corresponds to less than $0.5 \Phi_0$, continuous AUTORESETs may occur. The range of the AUTORESET is 0.0 - 4.5 volts dc.

Channel overload hardware continuously monitors channels 1-3 signal levels before the High Pass Filter. The outputs from each channel are wire-ORed together. If the signal on *any* channel exceeds ± 3 volts, and *any* of the HIGH PASS Filters are engaged, the microprocessor will be alerted. If the AUTORESET is ON for *any* channel, a RESET will be generated for all installed channels by the microprocessor.

The CHANNEL # ON/OFF field of the AUTORESET menu controls the RESET triggering from both the output voltage and channel overload conditions. For either of the AUTORESET conditions to be triggered, the ON selection for the channel must be enabled.

3.8.2.5. DISPLAY CONFIGURATION

DISPLAY CONFIGURATION		
CHANNEL	MULTIPLIER	EXPONENT
#1	1.00	0
#2	1.25	15
#3	1.00	0
AUX	1.00	3

Figure 11 Display Configuration Menu

The DISPLAY CONFIGURATION menu allows the user to scale the display reading and unit. The default settings for Multipliers and Exponents/Offsets values are 1.00 and 0 respectively. The front panel display will normally have a voltage value with a unit of "V". For channels 1, 2, or 3, if the multiplier is other than 1.00, the multiplier will be applied to the voltage reading. If the Exponent value is other than 0, the unit is "V" changed to read "E" for Exponent, and the Exponent value is displayed. For the Auxiliary channel, the display will use the result of $MX + B$, where M is the Multiplier and B is the OFFSET value.

This menu can be used for conversion of voltage to femtotesla or other units. The range of Multiplier is between -99.99 to +99.99. The range of Exponent is between -15 to +15.

3.8.2.6. CHANGE SYSTEM DEFAULT

SYSTEM DEFAULT		
INSTALLED CHANNELS:	#1	OFF
	#2	HTS
	#3	OFF
	AUX	OFF
HEATER ACTIVATION TIME	20	Sec
WAIT TIME AFTER HEATER	45	Sec
SUCCESSFUL TUNE VOLTAGE	2.00	Volt

Figure 12 System Default Menu

3.8.2.6.1. INSTALLED CHANNELS and CHANNEL CONFIGURATION

The SYSTEM DEFAULT menu allows the user to set the basic operating parameters for each iMAG channel. To install a SQUID channel, simply move the cursor to the Channel # using the SELECT key, and change the channel configuration from OFF to LTS or HTS. The operation of each channel requires the use of the correct iFL-301 Flux-Locked Loop configuration. The AUTOTUNE and AUTOTUNE after heat functions look at the configuration of each channel before performing the algorithms. Any channels configured, but not connected, will still be HEATED and AUTOTUNED. This will not damage the system or its components, but will slow the algorithms.

The AUXILIARY CHANNEL configuration menu selections are ON or OFF.

3.8.2.6.2. HEATER

The HEATER provides a 16 volt source which is used to raise the temperature of the SQUID Sensor above its' superconducting transition temperature, in order to purge any magnetic flux "trapped" in the sensor. Trapped flux can cause the SQUID Sensor to operate with less than optimal parameters. The heater current passes through a small resistor mounted close to the SQUID chip in the sensor package.

The HEATER ACTIVATION TIME is the amount of time (maximum of 50 seconds) that voltage is applied to each of the installed SQUID Sensor heater resistors. Because of the many applications for SQUID sensors and the conditions in which they are used, the amount of time required to heat the SQUID varies with the application.

The WAIT TIME AFTER HEATER is the amount of time (maximum of 50 seconds) that allows the SQUID Sensor to adequately cool below its' superconducting transition temperature before an AUTOTUNE is performed to optimize the SQUID parameters. To determine the appropriate HEAT and WAIT times perform the following procedure:

- 1) Enter the MANUAL TUNE menu.
- 2) Monitor the Analog Output BNC of the channel of interest with an oscilloscope.
- 3) Press the HEAT key on the iMC-303 Multichannel SQUID Controller front panel. The V/Φ_0 response signal on the oscilloscope should decrease when heated, until the magnitude of the signal drops to 0 volts dc. Notice the display on the iMC-303 Multichannel SQUID Controller. It should still be counting down the HEATER ON time. If it has already started to display the COOL DOWN TIME, the HEATER ACTIVATION TIME should be increased slightly. Start with a short time period (such as 15 seconds), and increase until the V/Φ_0 signal at the Analog Output BNC is at the 0 volt level for a few seconds before the COOL DOWN Time counter is activated.

The WAIT TIME AFTER HEATER should be set at a minimum of 35 seconds but should be about twice the HEATER ACTIVATION TIME.

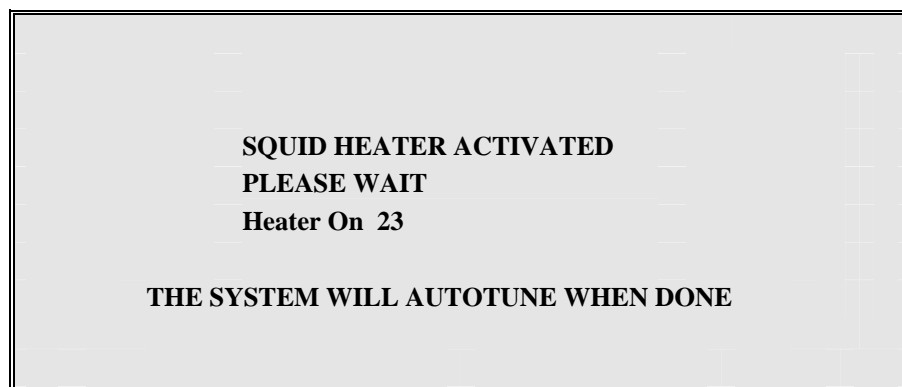


Figure 13 Heater Status Screen

3.8.2.6.3. SUCCESSFUL TUNE VOLTAGE

This field allows the user to set a minimum voltage level for the SQUID AUTOTUNE. It is the peak RMS magnitude of the periodic V/Φ_0 signal observed at the Analog Output on the rear panel while in the MANUAL TUNE screen. Upon each AUTOTUNE, the tune result will be compared to this voltage level. If the RMS voltage of the tuned SQUID is equal to or above this level the RUN menu will be automatically entered upon completion of the AUTOTUNE. If the tune voltage is less than this level, the MANUAL TUNE menu will be automatically entered upon completion of the AUTOTUNE.

3.8.2.7. MISC. MENU

This menu allows the user to select the FLL clock source and to enable the AUTO INITIALIZATION feature.

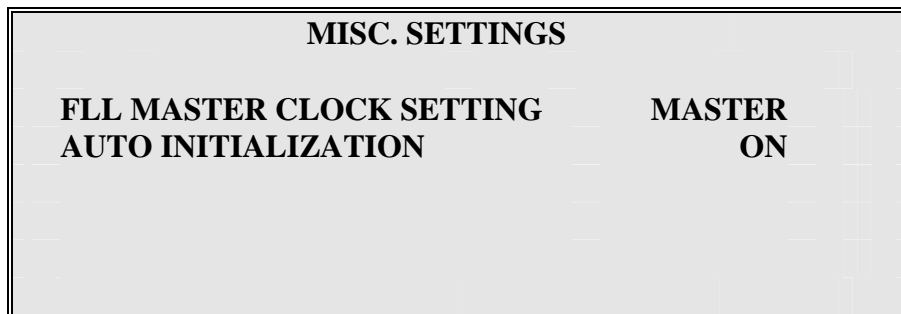


Figure 14 Misc. Settings Menu

The iMC-303 Multichannel SQUID Controller can be configured to support a multi-channel SQUID system consisting of more than the 3 channels supported by each iMC-303 Multichannel SQUID Controller. The rear panel CLOCK Input and Output BNCs provide a mechanism for all of the iFL-301 Flux-Locked Loops to be driven by a Master Clock. One iMC-303 Multichannel SQUID Controller is designated the “MASTER” and its “CLOCK Output” is connected to subsequent controllers’ “CLOCK Input”. These iMC-303 Multichannel SQUID Controllers are designated “SLAVE” . If only one iMC-303 Multichannel SQUID Controller is used, it must be designated “MASTER” .

If AUTO INITIALIZATION is set to ON, each installed Flux-Locked Loop channel will be checked for its RMS value against the SUCCESSFUL TUNE VOLTAGE upon power up. If the level is lower than the SUCCESSFUL TUNE VOLTAGE, the system will automatically perform an AUTOTUNE all channels. If any one of the installed channels does not pass the check, the system will automatically enter the MANUAL TUNE menu. If all passed, it will automatically enter the RUN menu. If AUTO INITIALIZATION is set to OFF, the iMC-303 Multichannel SQUID Controller will enter the RUN menu on power up.

3.8.3. TUNE

The easiest method for finding the optimum SQUID operating parameters is to take advantage of the iMAG AUTOTUNE algorithm. Regardless of the menu currently displayed, pressing the TUNE key causes the iMC-303 Multichannel SQUID Controller to enter the AUTOTUNE mode and determine the optimum SQUID TUNE parameters for each installed channel.

Once the TUNE key has been pressed, the iMC-303 Multichannel SQUID Controller will display the AUTOTUNE screen and perform the AUTOTUNE sequentially for each installed channel. (TUNING will be displayed for all installed channels and the cursor will flash in the field of the channel currently being tuned).

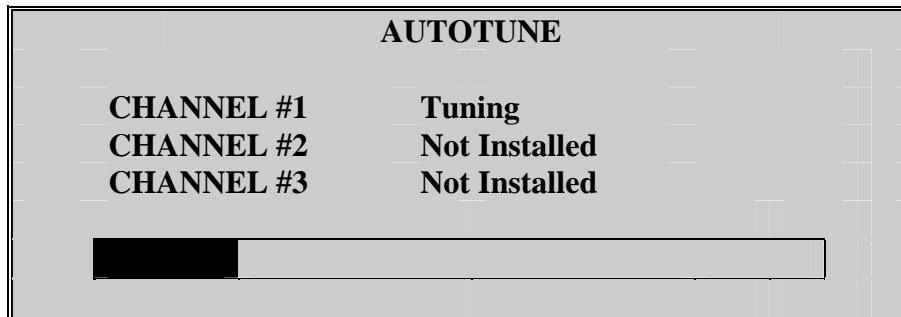


Figure 15 Autotune Screen

AUTOTUNE looks at the configuration (HTS or LTS) of the installed channels, executes the appropriate AUTOTUNE algorithm to determine the optimum TUNE parameters. Once the AUTOTUNE parameters have been determined, they are saved in non-volatile memory and are used to operate the SQUID sensor each time the RUN mode is entered.

The AUTOTUNE algorithm uses the SUCCESSFUL TUNE VOLTAGE in the CHANGE SYSTEM DEFAULT screen to determine whether the TUNE values resulting from the autotune are optimum. This SUCCESSFUL TUNE VOLTAGE is the peak RMS magnitude of the periodic V/Φ_0 signal observed at the Analog Output on the rear panel while in the MANUAL TUNE screen. If the TUNE voltage for all installed channels is greater than the SUCCESSFUL TUNE VOLTAGE, the system will automatically enter the RUN screen after completion of the AUTOTUNE. If the TUNE voltage for any of the installed channels is less than the SUCCESSFUL TUNE VOLTAGE, the system will automatically enter the MANUAL TUNE screen with channel 1 selected (whether it is installed or not). The SQUID may still operate, but this may indicate; "flux trapping", excessive RF interference, or inadequate shielding.

Chapter 4 Initial Power Up and Channel Installation

4. Initial Power Up and Channel Installation

4.1. Introduction

Before applying power to the iMC-303 Multichannel SQUID Controller, follow the INSTALLATION Procedure outlined in Chapter 2 of this manual. Once the initial inspection of the system components has been completed and the system interconnects have been made, the SQUID sensor is ready to cool in liquid nitrogen.

4.2. Cooling the SQUID Sensor

iMAG HTS SQUID sensors are mounted in a rigid assembly which provides mechanical support and protection for the SQUID.

Cool the SQUID as slowly as is practical. Slow cooling ensures that a minimal amount of thermal stress will occur, and reduces the chances of any ambient field becoming “trapped” in the SQUID. High levels of magnetic fields and electromagnetic interference can cause trapped flux, which can significantly degrade the performance of the system. Additional heating and/or additional shielding may be required to obtain desired performance.

4.3. Initial Power Up Sequence And Display

When the iMC-303 Multichannel SQUID Controller is first powered up, it goes through a series of internal tests. The results of these tests is displayed on the Self Test screen shown in figure 15. The ROM checksum and revision is also displayed here.

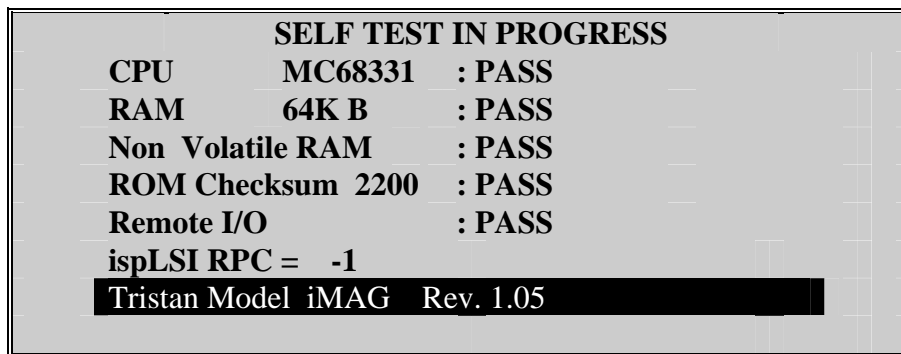


Figure 16 Self Test Screen

After the self test is complete, the iMC-303 Multichannel SQUID Controller defaults into the RUN mode and the screen will change to the RUN display. This process normally takes about 2 seconds. The iMC-303 Multichannel SQUID Controller will use the TUNE values stored in memory to operate the SQUID sensor.

4.4. Channel Installation and Using iMAG

The correct SQUID sensor and channel information should be verified in the SYSTEM DEFAULT menu prior to operating the iMC-303 Multichannel SQUID Controller with a SQUID sensor. The operation of each SQUID channel also requires the use of the correct iFL-301 Flux-Locked Loop configuration. To perform the channel configuration:

1. Press the SETUP key to display the SETUP menu.
2. Press the SELECT key to move the cursor to CHANGE SYSTEM DEFAULT.
3. Press the ENTER key.
4. Press the SELECT key to move the cursor to the channel you wish to install.
5. Use the INC or DEC key to change the channel configuration to match the iFL-301 Flux-Locked Loop and SQUID sensor connected to the rear panel.

The AUTOTUNE and HEATER functions poll the configuration of each channel before performing these functions. Channels configured, but not connected, will still be HEATED and AUTOTUNED. This will not damage the system or its components, but does slow the process.

The iMAG System should now be ready for basic use. Although the HEATER ACTIVATION TIME, WAIT TIME AFTER HEATER, and SUCCESSFUL TUNE VOLTAGE have all been preset at the factory, these parameters may require some adjustment due to the type of application, level of shielding, or amount of electromagnetic interference in the environment.

Chapter 5

Tuning and Operating the SQUID

5. Tuning and Operating the SQUID

5.1. Autotune

The best method to find the optimum SQUID operating parameters is to take advantage of the iMAG AUTOTUNE algorithm. Regardless of the menu currently displayed, pressing the TUNE key causes the iMC-303 Multichannel SQUID Controller to execute the AUTOTUNE algorithm and determine the optimum SQUID tune parameters for each installed channel.

The AUTOTUNE algorithm sequence is described below:

- 1) tune parameters are set to; BIAS+=0%, BIAS-=0%, MODULATION=15%(or last current value if >10%), SKEW=0%.
- 2) BIAS+ is swept from 0%-100%. The % corresponding to peak voltage is stored and BIAS+ set to that level. Peak is the maximum voltage in a $\pm 20\%$ window.
- 3) BIAS- is swept from 0%-100%. The % corresponding to peak voltage is stored and BIAS+ set to that level.
- 4) MODULATION is swept from 0%-100%. The % corresponding to peak voltage is stored and MODULATION set to that level.
- 5) BIAS+ and BIAS- are locked together and swept from 0%-100%. The % corresponding to peak voltage are stored and BIAS+ and BIAS- are set to those levels.
- 6) SKEW is swept from 0%-100%. The % corresponding to peak voltage is stored and BIAS+ set to that level.
- 7) The AUTOTUNE is complete.

Once the TUNE key has been pressed, the iMC-303 Multichannel SQUID Controller will display “Tuning” and perform the AUTOTUNE sequence described above for each installed channel. If the TUNE voltage detected is greater than the default SUCCESSFUL TUNE VOLTAGE setting, the RUN mode will be automatically entered. If the TUNE voltage detected is less than the DEFAULT setting, the MANUAL TUNE mode will automatically be entered. It is not necessary to perform an AUTOTUNE each time the power is removed from the iMC-303 Controller. Once the AUTOTUNE parameters have been determined, they are saved in non-volatile memory and are used to operate the SQUID Sensor each time the RUN key is pressed or on power up.

The AUTOTUNE should be repeated under the following conditions;

- 1) BIAS+ and BIAS- differ by more than 10%.
- 2) Tune voltage is significantly lower than previously known good values.
- 3) SQUID will not “lock”.
- 4) Range changed between $5 \Phi_0$ and $500 \Phi_0$.(GAINS of 1x-50x and 100x-500x)
The system will most likely perform adequately without retuning but for optimum performance, retuning may be necessary.
- 5) A large field or transient has caused the SQUID to loose “lock” and rail the output signal.

Connect an oscilloscope to the Analog Output for the appropriate channel on the rear panel to observe the sinusoidal SQUID V/Φ output signal. Press the HEAT key on the front panel and verify that the output signal decreases to zero before the "HEATER ON" message displayed by the iMAG Controller turns off. The sinusoidal SQUID output signal should then slowly reappear as the Sensor cools. If the SQUID output signal does not completely disappear, increase the HEATER ACTIVATION TIME until the SQUID output signal observed with the oscilloscope reaches zero Volts during a HEAT cycle. If AUTOTUNE continues to fail after the HEAT cycle has been activated and confirmed to operate properly, the TUNE parameters should be adjusted manually using the MANUAL TUNE menu. It should be verified that the maximum RMS output signal observed at the Analog Output BNC on the rear panel is larger than the default SUCCESSFUL TUNE VOLTAGE value. The SUCCESSFUL TUNE VOLTAGE value is displayed in the SYSTEM DEFAULT VALUES screen selectable from the SETUP menu. The SQUID may still operate if the TUNE parameters cannot be adjusted manually to reach the default SUCCESSFUL TUNE VOLTAGE value, but this can be a symptom of flux trapping, excessive rf interference or inadequate shielding. For further information, see Section 8.4 on RF INTERFERENCE and SHIELDING or contact Tristan Technologies.

5.1.1. Successful Tune Voltage

The AUTOTUNE algorithm uses certain benchmarks to determine whether the TUNE values determined during the AUTOTUNE sequence are optimum. One of these parameters is the SUCCESSFUL TUNE VOLTAGE. This is the maximum RMS voltage of the SQUID voltage-flux (V/Φ) output signal resulting from the AUTOTUNE. This setting should be set by the user for his/her specific operating environment.

5.1.2. Manual Tune

The optimum SQUID TUNE parameters are best found by using the AUTOTUNE algorithm. Because the TUNE parameters may vary with the type of circuit connected to the SQUID Input Circuit or type of measurements being taken, or even the level of electromagnetic noise present in the environmental setting, the user may choose to set these parameters manually. The TUNE parameters may be set manually by entering the MANUAL TUNE menu. The MANUAL TUNE menu is obtained pressing the SETUP key on the front panel from any menu. Select the MANUAL TUNE option by using the SELECT and ENTER keys.

MANUAL TUNE Procedure

- 1) Connect an oscilloscope to the Analog Output BNC of the appropriate channel on the rear panel. Set the oscilloscope for dc coupling, 2.0 volts/div. vertical scale, and 1 msec/div. horizontal scale.
- 2) Set the BIAS+, BIAS-, and SKEW levels to 0% and the Modulation level to the value indicated in the Sensor Test Report. It is possible that a new Modulation value may be determined during the MANUAL TUNE procedure, but this is generally the best starting point.

- 3) Increment the BIAS+ level until a signal is visible on the oscilloscope, then increment the BIAS- level until a similar peak is found. Maximize the signal using the INC and DEC keys to adjust the BIAS+ and BIAS- values.
- 4) Reduce the MODULATION to 0%, then increment it until the output on the oscilloscope reaches a maximum.
- 5) Increment the BIAS+ and BIAS- levels together until the maximum peak signal is found.
- 6) Readjust the MODULATION until the output on the oscilloscope reaches a maximum.
- 7) Next, adjust the SKEW parameter to maximize the oscilloscope signal.
- 8) If the TUNE levels just obtained are not within $\pm 20\%$ of those on the Sensor Test Report, it is possible that flux has been trapped in the SQUID Sensor. Perform a heat cycle and manually retune the SQUID. (Remember that an AUTOTUNE will always be automatically executed after a heat cycle).
- 9) Once the TUNE parameters have been determined, record them for future reference.

5.1.3. Reset

As discussed earlier, the SQUID responds to applied flux in a periodic fashion. Each periodic fluctuation is described as $1 \Phi_0$ or Flux Quantum. Since the SQUID is sensitive to changes in magnetic flux, there may be occasions when there is a relatively constant field which has caused the iMAG output to “flux jump” or lock on an operating point that is more than $1 \Phi_0$ from the zero field point. For instance, if a permanent magnet has been moved near the sensor. This effectively decreases the dynamic range of the system. Applying a RESET cancels the amount feedback current to the SQUID, then resumes normal operation within $1 \Phi_0$. After a RESET, the voltage out of the system is $0 \pm$ the amount of voltage which corresponds to $1 \Phi_0$ for that GAIN setting (set in the RUN display).

Chapter 6

Useful Operating Techniques

6. Useful Operating Techniques

6.1. Introduction

This section of the manual describes some techniques that are useful for operating SQUID systems.

6.2. Determining the Voltage/Flux Transfer Function (V/Φ_0)

The Voltage/Flux Transfer Function for each SQUID sensor is measured prior to shipment and is recorded on the test report. However, it is sometimes useful to re-measure this parameter.

This can be accomplished by introducing an offset to the operating point of the SQUID (while operating in the RUN mode) of just over $1 \Phi_0$, then RESETTING the SQUID. The change in output voltage will correspond to the voltage/flux transfer function (V/Φ_0) for that particular GAIN setting.

- 1) Assure the SQUID is TUNED and is operating in the RUN mode with the HIGH PASS filter set to OFF. Monitor the SQUID output voltage either on the display or at the analog output for the channel being used.
- 2) There are a few different methods to introduce offset in order to achieve a $1 \Phi_0$ change. One method is to use the OFFSET adjust in the RUN menu. Start by setting the GAIN to x100, OFFSET to 0%, and pressing the RESET Key. Refer to the SQUID Sensor or System Integration Test Report to determine the approximate V/Φ_0 value. The output displayed on the iMC-303 front panel should be less than the quantity shown in the Test Report. Note the actual voltage output. Using the INC and DEC Keys, change the OFFSET so that the voltage output on the display has changed by (approx. 20 %) more than the V/Φ_0 value described in the Test Report. Press the RESET Key. The change in the voltage output on the display will reflect the actual Voltage/Flux Transfer Function (V/Φ_0).
- 3) Another method of offsetting the SQUID operating point is to use a simple magnet. Remember that the shielding around the SQUID and the strength of the magnet have a major impact on the effectiveness of this technique. To offset the SQUID, slowly move a magnet closer to the sensor while observing the voltage output. When the output reaches a level greater than the recorded Voltage/Flux Transfer Function (V/Φ_0), place the magnet in a stationary position. The magnet must remain stationary. Press the RESET Key. Again, the change in the voltage output on the display will reflect the actual Voltage/Flux Transfer Function (V/Φ_0).

6.3. RF Interference and Shielding

The SQUID sensor is sensitive to electromagnetic interference. Interference may enter the system in a number of places such as the cabling, improper grounding of instruments in the test setup, and the SQUID input circuit. The iMAG has been specially designed to minimize the effect that interference has on the system. The majority of the interference does enter at the input of the SQUID.

Monitoring the Analog Output while in the MANUAL TUNE menu (see Section 6.2) is a good diagnostic of the effect interference is having on the system. The output should be a

clean signal, with a peak-to-peak amplitude of the same magnitude as recorded on the test report.

If the SQUID is sensing a signal which is greater than its bandwidth limit, the output will appear small and distorted. It is possible for the output not to appear at all if the interfering signal has an amplitude of $\Phi_0/2$.

By placing the SQUID in a small shield, the source of the interference may easily be determined.

6.4. Low Noise Operation

The following recommendations should be followed for operation in the lowest noise configuration.

- 1) Unplug the fan by removing the connector from JP10 on the iMAG Controller PC board. This will get reduce lone power and its harmonics.
- 2) Operate with OFFSET at -100% to reduce low frequency noise.

6.5. Bandwidth Adjust

The bandwidth of the FLL may be adjusted by turning the screw on R40. This is a gain pot that controls the amplitude of the triangles (the SQUID response while in tune mode). This is the open loop gain of the FLL which translates to the bandwidth of the locked loop mode of the FLL. The FLL is optimized for a 4.0 Vp-p triangle height, but will typically operate at a much lower triangle height with reduced slew rate.

Chapter 7

HTS SQUID Checkout Procedure

7. HTS SQUID Checkout Procedure

7.1. Introduction

To assist you in demonstrating the proper operation of your iMAG HTS SQUID System, the following test accessories are recommended:

- A simple liquid nitrogen dewar
- Mu-metal sensor shield and shield attachment collar (option)
- electronic watch with one second step increments

7.2. Procedure

- 1) Connect the iMAG controller and FLL using the composite cable. Be sure to connect the optical data and clock cables to the appropriate inputs on the controller and FLL by referring to the labels on the iMAG backpanel and the cables.
- 2) Connect the 77K SQUID sensor to the FLL/Model SP Cryogenic Cable assembly.
- 3) Place the Shield collar on the SQUID and the Mu-metal shield over the SQUID sensor and attach it to the collar with the screw provided.
- 4) Connect the analog output of the channel being used to an oscilloscope with the vertical axis set at 100mV/div and horizontal axis set at 100ms/div.
- 5) Place the watch underneath the dewar. This may be a slightly unstable arrangement. [You might try hanging it along the side as well with the watch face resting against dewar side]. **Do not insert the watch into the dewar!**
- 6) Insert the iMAG 77K sensor into the dewar and carefully add liquid nitrogen. Fill the dewar until it is about 3/4 full. Use safety glasses and protective gloves when handling liquid nitrogen.
- 7) Once the liquid nitrogen stops boiling vigorously, turn on the iMAG controller by pushing the **POWER** button. Press the HEAT button on the front panel. The SQUID will be heated and then AUTOTUNED.
- 8) If the RUN menu is not entered after the heat cycle, press TUNE.
- 9) After the system is in the RUN screen, verify that the HIGH PASS is set to off, and LO PASS is set to 5 Hz.

The output on the display bar graph on the RUN screen will oscillate approximately once every second and you will also see the voltage fluctuate. A trace approximating a square wave should also be seen on the oscilloscope.

Note that the amplitude of the detected signal is a function of the spacing between the SQUID and the watch. Your absolute amplitude may be significantly different. Repositioning either the SQUID and watch should dramatically affect the peak- to- peak voltage.

7.3. Troubleshooting

If your oscilloscope output or controller readout does not appear similar to Figure 3, several simple things can be checked. Verify the following:

- 1) proper interconnect of system components.

- 2) proper installation of shield.
- 3) adequate cryogen level.
- 4) sufficiently untrap SQUID.
- 5) SQUID properly tuned.

CHAPTER 8

iFL-301 Flux-Locked Loop

8. iFL-301 Flux-Locked Loop

iFL-301 Flux-Locked Loops are used in conjunction with HTS SQUID sensors provided with the iMAG Series of SQUID components. These units operate under the control of the iMC-303 Multichannel SQUID Control. The following discussion provides background and technical information about the iFL-301.

8.1. Background Information

The periodic outputs that are characteristic of the response of dc SQUIDs to external magnetic fields are not useful for practical applications. Generally speaking, a well behaved detector has an output that is linearly proportional to the input signal, not periodic. To make the output linear, a "flux-locked loop" is employed. This circuit applies a feedback flux to the loop to cancel any signal flux. Since the feedback signal is exactly equal to the input signal, one needs only to measure the feedback to know how much the flux changed at the input. A generic flux-locked loop comprises:

1. A modulation circuit that applies a small ac (usually square wave) flux to the SQUID loop. It has a peak-to-peak amplitude of $\frac{1}{2} \Phi_0$ and a typical frequency of 250 kHz. This circuit comprises a simple fixed-frequency and fixed-amplitude oscillator whose output is connected to a coil (the modulation coil) that couples this flux into the SQUID loop.
2. A phase-sensitive detector. This circuit uses the modulation signal as a reference and measures the amplitude and phase of the signal coming from the SQUID that is due to the modulation flux. It comprises a simple phase-sensitive detector connected to the "fundamental SQUID output" described above.

For those who are unfamiliar with phase-sensitive detectors, it is adequate to know that they require two inputs, a reference input and a signal input, to produce one output. The output voltage is proportional to the ac amplitude of input signals whose frequency and phase are the same as that of the reference signal. Other ac input signals (with a few notable exceptions, especially at harmonics) create no output. If the input signal is 180 degrees out of phase with the reference signal, the output voltage reverses polarity.

3. A feedback circuit that uses the output of the phase-sensitive detector to generate the feedback flux into the SQUID loop. This circuit can be as simple as a resistor connected between the output of the phase-sensitive detector and the modulation coil. (Typically, an integrator circuit is used in addition to more accurately cancel the input flux).

FLUX-LOCKED LOOP SUMMARY—Feedback is used to keep the total flux constant in the SQUID. Input signals are canceled by feedback and the feedback current is measured to determine the amplitude of the input signal.

8.2. iFL Configuration

The version of the flux-lock loop (iFL-301-H) provided with your iMAG system has been specially designed for use with the Tristan HTS sensor.

8.3. FLL Functions

The iFL-301 Flux-Locked Loop unit provides the following functions:

- Biasing of the SQUID—An alternating current bias is applied in order to reduce the sensor's inherent low frequency noise.
- Remote adjustment of Bias, Modulation and Skew levels are available from the iMC-303 Multichannel Control unit.
- Solid State heater—a circuit available to purge trapped magnetic flux from the SQUID.
- Dual Range feedback loop—Full-scale ranges of $\pm 5 \Phi_0$ and $\pm 500 \Phi_0$ are selected by the user. In the $\pm 5 \Phi_0$, the system provides the greatest sensitivity and the lowest noise (sensor limited noise). In the $\pm 500 \Phi_0$ range, the system provides the greatest dynamic range (electronics limited noise). The range is automatically selected by changing the GAIN of the SQUID in the "RUN" mode. The iMAG SQUID system operates in the $\pm 500 \Phi_0$ range when GAINS of x1-x50 are selected, and in the $\pm 5 \Phi_0$ range when GAIN is set to x100-x500.
- Dual bandwidth in the $\pm 5 \Phi_0$ range, 20 kHz (NORMAL) and 200 Hz (SLOW)
- DC Offset adjustment of $1.5 \Phi_0$ — This adjustment is performed by driving dc flux into the SQUID modulation coil.
- Two feedback modes: Internal and external. Selection made by internal jumper selection.
- Internal Bandwidth adjustment.

8.4. Functional Description

The Flux-Locked Loop circuitry is a second-order feedback loop plus required SQUID biasing circuitry (see figure below). It consists of the following:

- A SQUID signal preamplifier fabricated using a compound low-noise JFET and op-amp.
- A band-pass filter which rejects the Modulation and Bias frequencies.
- A balanced demodulator circuit which is used to translate the SQUID signal to base-band from its carrier frequency.
- A precision integrator plus a fixed-pole filter which provides the desired second-order loop response.
- The feedback drive circuit which drives the SQUID feedback coil.

Peripheral FLL circuitry includes:

- A heater driver that provides dc power to the SQUID heater resistor. This is activated from the control unit in order to drive the SQUID normal so that trapped flux may be purged.
- Local voltage regulators which provide dc power.
- A Command decoder circuit executes commands transmitted from the iMC-303 Multichannel SQUID Controller.
- A digital-to-analog converter circuit that generates levels for SQUID Bias, Modulation and Skew signals.

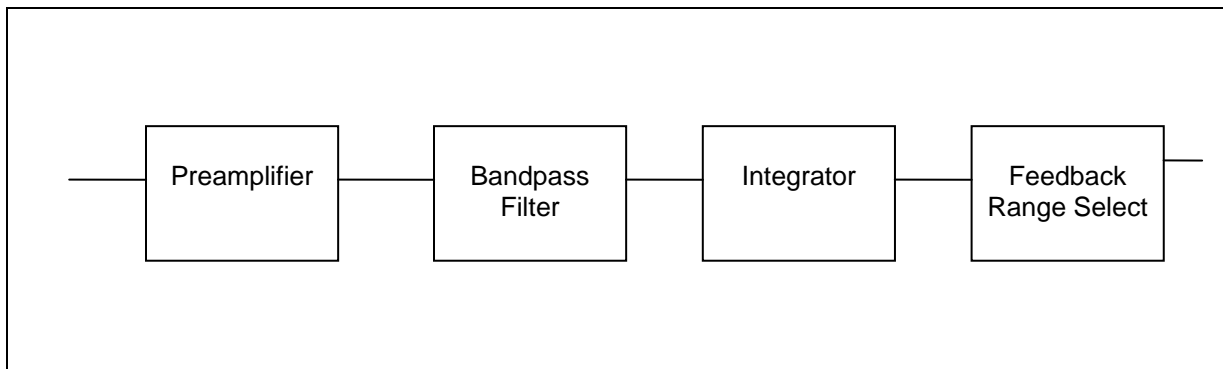


Figure 17 FLL Block Diagram

8.5. Control Unit Interface

A single 5-pin LEMO circular connector is used to connect dc power and Analog Output signals to the iFL-301 from the iMC-303 Controller.

Analog Output consists of a shielded twisted-pair. dc power includes wires for +8V, -8V, and ground.

Two fiber-optic cables are used to connect the 1 MHz clock and serial command data to the iFL-301 Flux-Locked Loop.

8.6. Physical Description

The iFL-301 contains a single electronic circuit board enclosed in a machined aluminum box. It measures 3.5" x 3.5" x 0.6" and weighs 7.5 oz.(210 grams).

The connection between the iFL-301 and the SQUID is made using an 18" pigtail wire assembly that has a strain relief at the unit end.

Connection to the iMC-303 Controller is via a five-pin LEMO type connector and two fiber-optic cables. The bundle of five copper wires and two fiber-optic links is assembled into a single 20' composite cable.

8.7. Product Specifications, iFL-301 H

The Tristan High Temperature Flux-Locked Loop uses an ac bias algorithm that effectively reduces the low-frequency noise normally produced by fluctuations in the critical currents of the SQUIDs' Josephson junctions.

The result of this biasing method is a clean, artifact free, FLL output spectrum that has a flat response to the specified bandwidth.

System Specifications	
Noise Density*	100 x 10 ⁻¹⁵ Tesla /√Hz Max between few Hz and 20 kHz
Full Scale Range*	± 500φ ₀ in GAIN selections of x1-x50 ± 5φ ₀ in GAIN selections of x100-x500
Bandwidth*	20 kHz in ± 500φ ₀ range Selectable 20 kHz (NORMAL) or 200 Hz (SLOW) in ± 5φ ₀ range

* Represents typical performance with SQUID

FLL to SQUID Interface	
Bias Drive	Differential, 0 to 300 x 10 ⁻⁶ Amps, square wave.
Bias Step Size Resolution	One part in 256
Modulation Drive	Differential, Amplitude 0 to 25 x 10 ⁻⁶ Amps
Modulation Resolution	One part in 256
Feedback	Internal or external depending on internal jumper selection. Differential.
DC Offset Flux	1.5φ ₀
Offset Resolution	One part in 256

FLL to Control Unit Interface	
Master Clock	1 MHz, Fiber Optic
Serial Command Data	1 MHz, Fiber Optic
Connector	5-pin LEMO connector, +8V _{DC} , -8V _{DC} , Ground, Analog Output, Analog Return
Analog Output	Raw FLL output, 3V, Band limited to 20 kHz, Output Impedance: 500 Ω
FLL power requirement	175 mA at 8V _{DC}

Table 2 FLL Specifications

Chapter 9

Specifications HTM-1

9. Specifications

9.1. Introduction

The iMAG dc SQUID System can be thought of as a very low noise current to voltage converter. Since current flows in the SQUID input circuit in the presence of magnetic flux, it can also be used as a flux to voltage converter. It operates as a four terminal device with the current input leads at low temperature and the voltage output leads at room temperature, with the transfer functions being very linear. The RMS input noise for a Tristan HTS SQUID is less than $30 \times 10^{-6} \Phi_0 / \sqrt{\text{Hz}}$ for frequencies greater than 1 Hz. In this expression, Φ_0 is the flux quantum, where $\Phi_0 = 2.07 \times 10^{-15}$ Weber or 2.07×10^{-15} Gauss/cm².

The input circuit of the HTS SQUID Sensor is currently fixed as a direct-coupled magnetometer. Other input configurations may be available for specific applications. For more details on the HTS Sensor input options, call Tristan Technologies.

The extreme sensitivity of the dc SQUID Sensor requires care in the design of the input circuit, especially with regard to grounding and shielding. The general rule is to have the input circuit well shielded for rf interference. Improper shielding will significantly degrade noise performance and slew rate.

9.2. System Specifications

9.2.1. Input Gain

Nine different Gain selections are available via the front panel in the RUN menu, or by remote interface. The selections are 1, 2, 5, 10, 20, 50, 100, 200, and 500.

The figure below shows the V / Φ_0 and ranges for the available gain selections. HTS SQUID sensor specifications may vary, so for actual sensor performance specifications, please refer to the SQUID Sensor or System Integration Test Report for your system.

Standard Range	Gain (iMAG front Panel)	mV/Φ_0
$\pm 500 \Phi_0$	x1	4.5
	x2	9.0
	x5	22.5
	x10	45.0
	x20	90.0
	x50	225.0
$\pm 5 \Phi_0$	x100	450 **
	x200	900
	x500	2250

Table 3 Gain vs Range

** the values in this table assume a V/Φ_0 value typical of HTS SQUIDS currently being fabricated. Use the V/Φ_0 value measured or that recorded in the System Integration Test report and scale accordingly.

9.2.2. Noise

The equivalent input noise for the HTS SQUID in the 1 Hz to 20 kHz range is less than $100 \text{ fT}/\sqrt{\text{Hz}}$ @ 1 Hz.

9.2.3. Frequency Response

The limit of the frequency response is determined by the SLEW selection in the RUN menu. The response is flat from dc to the 3 dB points given below.

SLEW mode	f_c (-3dB)
Slow	200 Hz
Normal	20 kHz

Table 4 FLL Frequency Response

9.2.4. Slew Rate

The FLL maximum Slew rate is about $6 \times 10^6 \Phi_0/\text{sec}$ for HTS SQUIDS. Full scale voltage swing at the iMC-303 output is ± 4.5 volts.

9.2.5. Input

Due to the unique characteristics associated with the materials used to fabricate HTS devices, it is not currently possible to supply HTS SQUID systems with input terminals. Therefore, all HTS iMAG systems come with an integral input coil attached to the SQUID, thereby creating an integrated magnetometer. For this reason, all signals must be inductively coupled to an HTS iMAG system.

For applications where one is only interested in detecting magnetic fields, one can simply observe the SQUID output to monitor the magnetic field at the input. In order to measure something other than magnetic field at the location of the SQUID sensor, it is necessary to build your own input circuit and inductively couple it to the SQUID. Tristan can optionally supply integral gradiometer pickup coils and other input circuits and we invite your inquiries for circuits to meet your specific needs.

9.2.6. Output

The Analog Output BNC for each channel is found on the instrument back panel. It is a pseudo differential type with an impedance of 500Ω , and full scale output of ± 4.5 volts.

9.2.7. Filtering

9.2.7.1. High Pass Filter

The High pass filter on the input circuit has selectable cut-off frequencies of dc coupled and 0.3 Hz.

9.2.7.2. Low Pass Filter

The low-pass filter on the output circuit is a 4-pole Butterworth with selectable cut-off frequencies of 5 Hz, 500 Hz, 5 kHz and Off. When Off is selected, the iMAG system will have a maximum bandwidth of 20 kHz.

9.2.8. Auxiliary Analog Input

An auxiliary analog input is provided via BNC on the back panel. This will allow a user provided signal to be digitized along with the SQUID signal. This input will have the same signal conditioning and filtering options as the SQUID channels.

Maximum input voltage is $\pm 3V$.

9.2.9. A/D converter

A two channel 16-bit, 20 kHz Analog-to-Digital converter handles the A/D conversion of the 3 SQUID channels as well as the AUX Analog Input channel.

9.2.10. User Interface

The user interface to the control unit is via interactions with a ten button keypad and an eight line LCD display. Menus allow easy access to all available functions.

9.2.11. Front Panel

The Front Panel is a membrane type with a ten key keypad and an LCD display showing 40 characters on each of 8 lines.

An LED on the panel indicates that the controller is in 'remote' mode (the controller is currently being accessed by the IEEE-488 or RS-232 ports and the keypad is locked out).

9.3. Remote Interfaces

IEEE-488 and RS-232 interfaces are both standard. All functions and read-outs available from the instrument may be completely controlled by either interface via remote computer.

9.3.1. IEEE-488 Interface

The IEEE-488 interface allows complete remote control of the instrument as well as the ability to read all information to full internal accuracy.

The interface is compliant with IEEE Standard 488-1978.

9.3.2. RS-232 Interface

The RS-232 interface allows full operation of the instrument, as does the IEEE-488 interface. The Baud rate is selected by the front panel. Maximum Baud rate is 38,400.

9.4. Mechanical, Form Factors

9.4.1. Enclosure

The iMAG enclosure measures 321mm wide, 121mm high, 300 mm deep (12.6in x 4.8in x 11.8in) and weighs 6.3 kg (14 lbs.). It may be used either stand-alone or incorporated in an instrument rack with an optional rack mount kit.

9.5. Power

9.5.1. AC Power Requirements

The instrument requires single-phase AC power of 50 to 60 Hz. Voltages are selectable at the power entry module for 100,120,220, or 240 V_{AC}. Tolerance on voltages is $\pm 10\%$.

9.5.2. Instrument Fusing

A user-replaceable fuse is mounted in the power entry module. This module also includes a spare.

The fuse required is a 3A slow-blow for 100 and 120 V_{AC}, and 1.5 A slow-blow for 220, or 240 V_{AC}.

9.5.3. Power Grounding Requirements

The Ground wire on the AC line cord must be connected to a safety ground that does not normally carry electrical current. This safety ground becomes the Chassis Ground of the instrument and is used as the ground point for all cable shields. Thus, it is important to ensure a good quality connection.

Appendix A Remote Interface Commands

Appendix A: Remote Interface Commands:

Remote interface commands are used with a GPIB (IEEE-488) or RS232 interface. All commands are applicable to IEEE-488, but some are specific to IEEE-488 use. The GPIB common commands and GPIB query commands (described below) cannot be used with RS232.

These commands are broken down into 3 major types.

1. **GPIB common commands(*XXX).** These types of commands always have a '*' as the first character and do not have a '?' as the fifth character.
2. **Generic GPIB query commands(*XXX?).** These types of commands always have '*' as the first character and '?' as the fifth character.
3. **iMAG device dependent commands.** If the command is not a GPIB common or GPIB query command, this function is assumed to be an iMC-303 Multichannel SQUID Controller command. e.g. SHPF; QSAMP?1;

Some of the iMC-303 Multichannel SQUID controller commands have more than 1 parameter. The **separator** between the parameters is an ASCII comma ",", and the **terminator** is an ASCII semicolon ";". For input, spaces, CR and LF characters are stripped out by the parser. You may use them when appropriate to make your source code more readable. The character string returned by the iMC-303 in response to a query is terminated by (a) semicolon ';' character and a linefeed ('\n') character, and is not null terminated.

CAUTION: There is **NO** separator (,) between
the command and its first parameter!

Reference : Please refer to the *IEEE Standard Codes, Formats, Protocols and Common Commands manual (ANSI/IEEE Std 488.2-1987)* for the definition and intent of IEEE Common Commands and IEEE Common Queries.

Appendix B contains sample programs with both RS232 and GPIB protocol.

Table 5 Summary of Remote Interface Commands

Name	Description
Common IEEE Commands	
*CLS	Clear Status
*ESE	Event Status Enable
*OPC	Operation Complete
*RST	Reset Command
*SRE	Service Request
*WAI	Wait-to-Continue
Common IEEE Query	
*ESE?	Event Status Enable Query
*ESR?	Event Status Register Query
*IDN?	Identification Query
*OPC?	Operation Complete Query
*SRE?	Service Request Enable Query
*STB?	Status Byte Query
iMAG Commands	
QADDR?	Query GPIB (IEEE-488) address
QAINIT?	Query auto initialization setting
QARESET?	Query auto-reset settings
QDACQ?	Query high-speed data acquisition parameters
QDAPCK?	Query frequency of SRQ in high-speed data acquisition
QDPCHAN?	Query number of current display channel (1-4)
QDPMPL?	Query display multiplier for channels 1-4
QDPXO?	Query display exponent/offset for channels 1-4
QFLLMCLK?	Query FLL master clock setting
QGAIN?	Query gain value for channels 1-4
QHPF?	Query high pass filter value for channels 1-4
QISTATE?	Query the instrument state

Name	Description
QLPF?	Query low pass filter value for channels 1-4
QOFFSET?	Query offset value for channels 1-3
QSAMP?	Query a voltage sample for channels 1-4
QSLEW?	Query slew rate value for channels 1-3
QSYSPARAM?	Query system default values
QTBIASN?	Query manual tune negative bias level for channels 1-3
QTBIASP?	Query manual tune positive bias level for channels 1-3
QTMOD?	Query manual tune modulation level for channels 1-3
QTSKEW?	Query manual tune skew level for channels 1-3
QTUNESTAT?	Query status of an auto-tune for channels 1-3
QUERREG?	Query User Error Registers
SAINIT	Set auto initialization parameter
SARESET	Set auto-reset parameters
SARM	Activate high-speed data acquisition
SDACQ	Set high-speed data acquisition parameters (See next page)
SDAPCK	Set frequency of SRQ in high-speed data acquisition
SDARM	Halt high-speed data acquisition/test
SDPCHAN	Set display channel to channel 1-4
SDPMPL	Set display multiplier for channels 1-4
SDPXO	Set display exponent/offset for channels 1-4
SFLLMCLK	Set FLL master clock
SGAIN	Set gain value for channels 1-4
SHEAT	Activate SQUID heater
SHPF	Set high pass filter value for channels 1-4
SISTATE	Set the instrument state
SLEW	Set slew rate for channels 1-3

Name	Description
SLLOCK	Set local lock-out
SLPF	Set low pass filter value for channels 1-4
SOFFSET	Set offset value for channels 1-3
SRATE	Set format of data stream in high-speed data acquisition
SRESET	Set flux-lock loop to reset
STBIASN	Set manual tune negative bias level
STBIASP	Set manual tune positive bias level
STMOD	Set manual tune modulation level
STSKEW	Set manual tune skew level
SYSCHAN	Set system default values - install channels
SYSHEAT	Set system heater activation time
SYSVOLT	Set successful tune voltage value
SYSWAIT	Set system wait time after heater
SUERREG	Enable User Error Registers

IEEE Command Reference

***CLS**

Format: *CLS;

iMAG Response: None

Description:

The Clear Status command clears the Standard Event Status Register's bit 4 and bit 5 (Execution Error bit, and Command Error bit), and the content of Execution Error Register and Command Error Register. This command also resets the input and output character buffers.

Related Commands:

*ESE, *ESE?, *ESR?, *SRE, *SRE?, *STB?, SUERREG, QUERREG?, *ESE

***ESE**

Format: *ESE;

iMAG Response: None

Description:

The Event Status Enable command sets the Standard Event Status Enable Register bits as defined by the IEEE 488.2-1987 standard.

Related Commands:

*CLS, *ESE?, *ESR?, *SRE, *SRE?, *STB?, SUERREG, QUERREG?

***OPC**

Format: *OPC;

iMAG Response: None

Description:

The Operation Complete command sets the Standard Event Status Register's bit 0 (Operation Complete bit) when all the pending operations are completed.

Related Commands:

*OPC?, *ESE, *ESE?, *ESR?, *SRE, *SRE?, *STB?

***RST**

Format: *RST;

iMAG Response: None

Description:

The Reset command resets the iMC-303 Multichannel SQUID Controller remotely. This is equivalent of cycling the power on the iMC-303 Multichannel SQUID Controller.

Related Commands: None.

***SRE**

Format: *SRE<register enable value>;

iMAG Response: None

Description:

The Service Request Enable command sets the Service Request Enable Register as defined by the IEEE 488.2 - 1987 document.

Related Commands:

*SRE?

***WAI**

Format: *WAI;

iMAG Response: None

Description:

The Wait-to-Continue command is a synchronization command. It prevent the iMC-303 Multichannel SQUID Controller from executing any further commands or queries until there is no operation pending. *Since all iMC-303 Multichannel SQUID Controller commands are instantaneous executable commands, this command is seen as a “no operation command”.*

Related Commands:

*OPC, *OPC?

IEEE Query Command Reference

***ESE?**

Format: *ESE?;

iMAG Response:

A 4 byte ASCII character string containing a value ranging from 0 to 255.

Example: *ESE?;255;

Description:

The Standard Event Status Enable Query requests the Standard Event Status Enable Register content in the iMC-303 Multichannel SQUID Controller. The content of the register can be interpreted based on the IEEE 488.2 -1987 document.

Related Commands:

*CLS *ESE *ESR? *SRE *SRE? *STB? SUERREG QUERREG?

***IDN?**

Format: *IDN?;

iMAG Response:

A 36 byte ASCII character string containing the device identification in the following format: "TRISTAN Model iMAG, *revision number*".

Example: *IDN?; CONDUCT Model iMAG Rev 1.04;

Description:

The Identification Query requests device identification. The intent is to determine the unique identification of devices on the bus.

Related Commands:

*RST

***OPC?**

Format: *OPC?;

iMAG Response:

A 2 byte ASCII character string containing the value "1".

Example: *OPC?;1;

Description:

The Operation Complete Query returns a "1" when all pending operations are completed.

Related Commands:

*OPC, *ESE, *ESE?, *ESR?, *SRE, *SRE?, *STB?

***SRE?**

Format: *SRE?;

iMAG Response:

A one byte value, ranging from 0 to 63 or 128 to 191.

Example: *SRE?;255;

Description:

The Service Request Enable query requests the Service Request Enable Register content. The contents are defined by the IEEE 488.2 - 1987 document.

Related Commands:

*SRE

***STB?**

Format: *STB?;

iMAG Response:

A one byte value, ranging from 0 to 63 or 128 to 191.

Example: *STB?;115;

Description:

The Read Status Byte query requests the Status Byte Register contents. The contents are defined by the IEEE 488.2 - 1987 document.

Related Commands:

*CLS, *ESE, *ESR?, *SRE, *SRE?

iMAG Commands Reference

QADDR?

Format: QADDR?;

iMAG Response:

A three byte value indicating the GPIB address of the instrument.

Example: QADDR?; 15;

Description:

Inquire about the current IEEE-488 (GPIB) address setting for the instrument. The number will be between 0 and 15. If the remote interface is set to RS232, the number 232 will be returned.

Related Commands:

SADDR

QAINIT?

Format: QAINIT?;

iMAG Response:

A one byte value indicating automatic initialization selection. 0 is OFF. 1 is ON.

Example: QAINIT?; 1;

Description:

Inquire about the automatic initialization setting. For an ON setting, upon power on, the iMAG controller will first check the installed channels and compare their respective triangle height against the GOOD TUNE VOLTAGE. If any one of the installed channels is less than the GOOD TUNE VOLTAGE, the system will do an AUTOTUNE for all installed channels. If the system pass the AUTOTUNE, it will proceed to the RUN screen. Otherwise, it will remained in the AUTOTUNE screen to show the AUTOTUNE results. For an OFF setting, upon power on, the iMAG controller will proceed to the RUN screen without going through the auto-initialization.

Related Commands:

SAINIT?

QARESET?

Format: QARESET? <Channel 1-3>;

iMAG Response:

An 8 byte ASCII character string of 2 parameters, each ended with a semicolon. The first parameter is the value 1 or 0, indicating if auto-reset is turned on or off for that channel. The second parameter is a value between -4.5 and 4.5, indicating the reset voltage.

Example: QARESET?1; 0; 0.0;

Description:

Inquire about the current auto-reset settings for channels 1-3.

Related Commands:

SARESET

QDACQ?

Format: QDACQ?;

iMAG Response:

Returns a 6 byte ASCII character string with 2 parameters, each ended with a semi-colon. Parameter 1 is the channel configuration, parameter 2 is the composite data acquisition rate.

Example: QDACQ?; 1; 3;

Description:

Inquire about the current high-speed data acquisition channel configuration and rate.

Related Commands:

SDACQ, SARM, SDARM, SRATE, SDAPCK, QDAPCK?

QDAPCK?

Format: QDAPCK?;

iMAG Response:

Returns a 4 byte ASCII character string containing a number from 1 to 400. This number corresponds to how often the SRQ line is set during high-speed data acquisition. For instance, a rate of 100 means the iMC-303 will output 100 packets of data and then set the SRQ line. A packet contains 16 samples (32 bytes) by default. You can change the packet size using the SRATE command.

Example: QDAPCK?; 100;

Description:

Inquire about the current high-speed data acquisition SRQ frequency.

Related Commands:

SDAPCK, SARM, SDARM, SRATE, SDACQ, QDAPCK?

QDPCHAN?

Format: QDPCHAN?;

iMAG Response:

Returns a 3 byte ASCII character string containing a number from 1 to 4. Channels 1 to 3 are the Flux Locked loops and Channel 4 is the Auxiliary Analog input.

Example: QDPCHAN?; 1;

Description:

Inquire about the current controller display channel.

Related Commands:

SDPCHAN

QDPMPL?

Format: QDPMPL? <Channel 1-4>;

iMAG Response:

A 7 byte ASCII character string containing a value between -99.99 and +99.99.

Example: QDPMPL?1; 1.00;

Description:

Inquire about the multiplier value for a channel.

Related Commands:

SDPMPL

QDPXO?

Format: QDPXO? <Channel 1-4>;

iMAG Response:

A 4 byte ASCII character string containing a value between -99.99 and +99.99.

Example: QDPXO?1; 0;

Description:

Inquire about the exponent and offset value for a channel.

Related Commands:

SDPX0

QFLLMCLK?

Format: QFLLMCLK?;

iMAG Response:

A 4 byte ASCII character string containing the value 1 or 0. "1" indicates that the FLL master clock is set to Master, "0" indicates Slave.

Example: QFLLMCLK?; 1;

Description:

Inquire about the FLL master clock setting.

Related Commands:

SFLLMCLK

QISTATE?

Format: QISTATE?;

iMAG Response:

A 3 byte ASCII character string containing a value between 0 and 4. "0" indicates that the instrument is in OFF mode, "1" indicates RUN mode, "2" indicates MANUAL TUNE mode, "3" indicates that an AUTO-TUNE is in progress and "4" indicates that the SQUID heater is activated.

Example: QISTATE?; 1;

Description:

Inquire about the current state of the instrument.

Related Commands:

SISTATE, SHEAT

QGAIN?

Format: QGAIN? <Channel 1-4>;

iMAG Response:

One of the following 5 byte ASCII character strings: " x1;", " x2;", " x5;", "x10;", " x20;", " x50;", " x100;", " x200;", " x500;".

Example: QGAIN?1; x1;

Description:

Inquire about the GAIN value for the specified channel.

Related Commands:

SGAIN

QHPF?

Format: QHPF? <Channel 1-4>;

iMAG Response:

One of the following 7 byte ASCII character strings: “ DC;” or “ 0.3Hz;”.

Example: QHPF?1; DC;

Description:

Inquire about the High Pass Filter value setting for the specified channel.

Related Commands:

SHPF

QLPF?

Format: QLPF? <Channel 1-4>;

iMAG Response:

One of the following 7 byte ASCII character strings: “ OFF;”, “ 500Hz;”, “ 5kHz;”, “5Hz;”

Example: QLPF?1; OFF;

Description:

Inquire about the Low Pass Filter value setting for the specified channel.

Related Commands:

SLPF

QOFFSET?

Format: QOFFSET? <Channel 1-3>;

iMAG Response:

A 5 byte ASCII character string containing a value between -100 and +100.

Example: QOFFSET?1; -1;

Description:

Inquire about the OFFSET setting for the specified channel.

Related Commands:

SOFFSET

QSAMP?

Format: QSAMP? <Channel 1-4>;

iMAG Response:

A 12 byte ASCII character string containing a value between -4.5V to +4.5V, or the 17 byte message “Channel disabled;”.

Example: QSAMP?1; 1.350V ;

Inquire about the current sensor voltage for the specified channel.

Related Commands:

SARM, STEST, SDARM, SDACQ, QDACQ

QSLEW?

Format: QSLEW? <Channel 1-3>;

iMAG Response:

One of the following 7 byte ASCII character strings: “ SLOW;”, “ NORMAL;”.

Example: QSLEW?1;NORMAL;

Description:

Inquire about the slew setting for the specified channel.

Related Commands:

SLEW

QSYSPARAM?

Format: QSYSPARAM?

iMAG Response:

A 32 byte ASCII character string of seven parameters, each ended with an semicolon “;”. The first three strings are either “OFF;”, “LTS;”, or “HTS;”, denoting whether the respective channel is configured for LTS (low temperature sensor), HTS (high temperature sensor), or not installed. The fourth string is either “YES;” or “NO;”, indicating whether or not the auxiliary channel is installed. The fifth string is a value between 1 and 50, and it denotes the system heater activation time in seconds. The sixth string is a value between 1 and 50, and denotes system wait time after the heater activation. The seventh string is a value between -4.5 and 4.5, and it denotes the successful tune voltage.

Example: QSYSPARAM?;LTS;HTS;OFF; YES; 10; 12; 2.00;

Description:

Inquires about the system default values.

Related Commands:

SYSCHAN, SYSHEAT, SYSVOLT, SYSWAIT

QTBIASN?

Format: QTBIASN? <CHANNEL 1-3>;

iMAG Response:

A 5 byte ASCII character string containing a value between 0 and 100.

Example: QTBIASN?1; 0;

Description: Inquires about the manual tune negative bias setting for the specified Flux Lock Loop channel. The response is a percentage value (Applies to Flux Lock Loop “-H” configuration, designed for use with HTS sensors).

Related Commands:

STBIASN

QTBIASP?

Format: QTBIASP? <CHANNEL 1-3>;

iMAG Response:

A 5 byte ASCII character string containing a value between 0 and 100.

Example: QTBIASP?1; 57;

Description:

Inquires about the manual tune positive bias setting for the specified Flux Lock Loop channel. The response is a percentage value.

Related Commands:

STBIASP

QTMOD?

Format: QTMOD? <CHANNEL 1-3>;

iMAG Response:

A 5 byte ASCII character string containing a value between 0 and 100.

Example: QTMOD?1; 29;

Description:

Inquires about the manual tune Modulation setting for the specified Flux Lock Loop channel. The response is a percentage value.

Related Commands:

STMOD

QTSKEW?

Format: QTSKEW? <CHANNEL 1-3>;

iMAG-1 Response:

A 5 byte ASCII character string containing a value between 0 and 100.

Example: QTSKEW?1; 0;

Description:

Inquires about the Manual Tune SKEW percentage value (Applies to Flux Lock Loop “-H” configuration, designed for use with HTS sensors).

Related Commands:

STSKEW

QTUNESTAT?

Format: QTUNESTAT?;

iMAG-1 Response:

A 9 byte ASCII character string containing 3 parameters, each ended with a semicolon “;”. Each of the three parameters represents the AUTO-TUNE status of one of the three flux-lock loop channels. The value “0” indicates that the channel auto-tuned successfully. The value “1” indicates that the channel failed to auto-tune. The value “2” indicates that the channel is currently being auto-tuned, and “3” indicates that the channel is not installed.

Example: QTUNESTAT; 1; 3; 3;

Description:

Inquires about the AUTO-TUNE status of the 3 flux-lock loop channels.

Related Commands:

QISTATE?, SISTATE, SYSVOLT

QUERREG?

Format: QUERREG?<1=Command Error Register, 2=Execution Error Register>;

iMAG Response:

One ASCII byte indicating the register contents in decimal.

Example: QUERREG?1;5;

Description:

Queries the User Error registers. This command will also clears the register content.

Command Error Register Bit Definition:

Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1
Not Used	Not Used	Not Used	Not Used	Not Used	Bad Parameter	Unterminated Command	Unknown Command

Execution Error Register Bit Definition:

Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1
Not Used	Not Used	Not Used	Transmit Buffer Overflow	Parity Error	Unknown GPIB Error	Receive Buffer Overflow	Transmit Buffer Under flow

Related Commands:

SUERREG

SADDR

Format: SADDR<0-15 or 232>;

iMAG Response: None

Description:

Set the IEEE (GPIB) address for the instrument. This number must be between 0 to 15. The system default is 15. For an RS232 interface, "SADDR 232;" will do the initial switch from IEEE to RS232.

Related Commands:

QADDR?

SAINIT?

Format: SAINIT<1=ON, 0 = OFF>;

iMAG Response: None.

Example: SAINIT 0;

Description:

Sets the automatic initialization setting. For an ON setting, upon power on, the iMAG controller will first check the installed channels and compare their respective triangle height against the GOOD TUNE VOLTAGE. If any one of the installed channels is less than the GOOD TUNE VOLTAGE, the system will do an AUTOTUNE for all installed channels. If the system pass the AUTOTUNE, it will proceed to the RUN screen. Otherwise, it will remained in the AUTOTUNE screen to show the AUTOTUNE results. For an OFF setting, upon power on, the iMAG controller will proceed to the RUN screen without going through the auto-initialization. Manufactory default sets it to ON.

Related Commands:

QAINIT?

SARESET

Format: SARESET<Channel 1-3>,<0=OFF, 1=ON>,
<Reset voltage= -4.5 to 4.5>;

iMAG Response: None

Description:

Sets the Auto-reset parameters for each flux locked loop channel. Setting Auto-reset to ON will cause that channel to Auto-tune each time the system is reset, or the power is cycled. The default is ON.

Related Commands:

QARESET?

SARM

Format: SARM;

iMAG Response:

Continuous stream of voltage samples from the iMC-303 Multichannel SQUID controller.

Description:

Triggers the high-speed data acquisition mode. When SARM is received, the front panel indicates high-speed data acquisition mode, and a continuous stream of data is sent across the remote interface (GPIB only) until the SDARM command is received.

Before the SARM command is sent, the user should set up the data acquisition parameters using SYSCHAN, SRATE, SDAPCK and SDACQ commands. SYSCHAN is used to enable the SQUID channels. SDACQ selects the channels to acquire data from, and the composite rate. SRATE and SDAPCK are used to change acquisition defaults.

Example: SYSCHAN1,1;

 SDACQ 1,3;

 SARM;

The above example sets the instruments state to RUN mode, sets channel 1 for data collection with a data transfer rate of 20,000 words per second. See Appendix C for further descriptions and examples.

Related Commands:

SDARM, SRATE, SDACQ, QDACQ?, SDAPCK, QDAPCK?

SDACQ

Format: SDACQ <Channel select= 1-11>, <Speed Select = 0-3>;

Commands	Channel Select	= Channels	Speed Select	= Speed
SDACQ 1,<0-3>;	1	1	0, 1, 2, 3	2.5K, 5K, 10K, 20K
SDACQ 2,<0-3>;	2	2	0, 1, 2, 3	2.5K, 5K, 10K, 20K
SDACQ 3,<0-3>;	3	3	0, 1, 2, 3	2.5K, 5K, 10K, 20K
SDACQ 4,<0-3>;	4	AUX	0, 1, 2, 3	2.5K, 5K, 10K, 20K
SDACQ 5,<0-2>;	5	1,3	0, 1, 2	2.5K, 5K, 10K
SDACQ 6,<0-2>;	6	2,AUX	0, 1, 2	2.5K, 5K, 10K
SDACQ 7,<0-1>;	7	1,2,3,AUX	0, 1	2.5K, 5K
SDACQ 8,<0-1>;	8	1,2	0, 1	2.5K, 5K
SDACQ 9,<0-1>;	9	1,AUX	0, 1	2.5K, 5K
SDACQ 10,<0-1>;	10	2,3	0, 1	2.5K, 5K
SDACQ 11,<0-1>;	11	3,AUX	0, 1	2.5K, 5K

iMAG Response: none.

Description:

Used to configure the high-speed data acquisition parameters. Parameter 1 selects the channel(s) to be sampled. Parameter 2 selects the data acquisition rate for each individual channel.

Related Commands:

SARM, SDARM, QDACQ?, SRATE, SDAPCK, QDAPCK?

SDAPCK

Format: SDAPCK;

iMAG Response:

Sets the rate which determines how often the SRQ line is set during high-speed data acquisition. For instance, a rate of 100 means the iMC-303 will output 100 packets of data and then set the SRQ line. A packet contains 1 to 16 samples (2-32 bytes). The default is 16, and can be changed using the SRATE command.

Example: QDAPCK?; 100;

Description:

Inquire about the current high-speed data acquisition SRQ frequency.

Related Commands:

QDAPCK, SARM, SDARM, SRATE, SDACQ, QDACQ?

SDARM

Format: SDARM;
iMAG Response: none.

Description:

Halts high-speed data acquisition. When SDARM is received, the front panel returns to run mode, and the stream of data from the iMAG is halted.

Related Commands:

SARM, SDACQ, QDACQ?, SRATE, SDAPCK, QDAPCK?

SDPCHAN

Format: SDPCHAN <1-4>;

iMAG Response: None

Description:

Sets the front panel display channel. Channels 1 to 3 are the Flux Locked Loops, 4 is the Auxiliary analog input channel. The default display channel is 1.

Related Commands:

QDPCHAN?

SFLLMCLK

Format: SFLLMCLK <0=Slave, 1=Master>;

iMAG Response: None

Description:

Sets the FLL master clock setting. “0” sets the FLL master clock to Slave, “1” sets it to Master. The default is 1. This is to link multiple iMAG controllers.

Related Commands:

QFLLMCLK?

SGAIN

Format: SGAIN<Channel 1-4>,<1=x1, 2=x2, 3=x5, 4=x10, 5=x20, 6=x50, 7=x100, 8=x200, 9=x500>;

iMAG Response: None.

Description:

Sets the Gain value for the specified channel. Parameters 1-9 are valid for channels 1-3, parameters 1-6 are valid for channel 4 (auxiliary). The default gain for each channel is x1.

Related Commands:

QGAIN?

SHEAT

Format: SHEAT;

iMAG Response: None.

Description:

Activates the system SQUID heater. When SHEAT is received, the front panel will indicate that the system heater is active. The system will go into a heat cycle, followed by a cool down period. The command SYSHEAT is used to set the heater activation time, and SYSWAIT sets the time for the cool down period. An auto-tune follows the cool down period.

Related Commands:

SYSHEAT, SYSWAIT, SYSVOLT, QISTATE?, QSYSPARAM?, QTUNESTAT?

SHPF

Format: SHPF <Channel 1-4>,<0=DC, 1= 0.3Hz>;

iMAG Response: None.

Description:

Sets the High Pass Filter value for specified channel. The default is "DC".

Related Commands:

QHPF?

SISTATE

Format: SISTATE<0=OFF, 1=RUN, 2=MANUAL TUNE, 3=AUTOTUNE>;

iMAG Response: None.

Description:

Sets the system state of the iMAG. When the system is in "OFF" mode, voltage samples are not displayed on the front panel. In "RUN" mode samples are displayed on the front panel, and high-speed data acquisition can be triggered. In "TUNE" mode the user can perform a "manual tune" by adjusting the positive bias and modulation. When set to "AUTOTUNE", the system automatically tunes the active channels, and then displays the results on the front panel. QTUNESTAT? can be used to check the status of each channel as it is being tuned, or to view the results after the tune is complete. The default is 0.

Related Commands:

QISTATE?, QTUNESTAT?, SHEAT

SLEW

Format: SLEW<Channel 1-3>,<0=NORMAL, 1=SLOW>;

iMAG Response: None.

Description:

Sets the system Slew value. "SLOW" can only be used if the gain is set to x100 or higher. The default is "NORMAL".

Related Commands:

QSLEW?

SLLOCK

Format: SLLOCK<0 = no lockout, 1 = local lockout>;

iMAG Response:

Once the Local Lockout mode is set, the front panel keyboard is disabled until the LOCAL key is pressed or SLLOCK 0 command is invoked from remote I/O.

Description:

On the GPIB interface, once the Local Lockout mode is set, the front panel **REM** LED is lit, and the front panel keyboard is disabled until the LOCAL key is pressed or SLLOCK 0 command is invoked from the remote I/O. For RS232 interface, the **REM** LED is not changed. The front panel keyboard is disabled when SLLOCK 1 command is invoked.

Related Commands:

QLLOCK?

SLPF

Format: SLPF <Channel 1-4>,<0=OFF,1=500 Hz, 2=5000 Hz, 3=5 Hz>;

iMAG Response: None.

Description:

Sets the Low Pass Filter for the specified channel. The default is "OFF".

Related Commands:

QLPF?

SOFFSET

Format: SOFFSET <Channel 1-3>,<-100 to +100>;

iMAG Response: None.

Description:

Sets the OFFSET percentage value for the specified channel. Value must be a value within the range of -100 to +100 Volts. The default is 0.

Related Commands:

QOFFSET?

SRATE

Format: SRATE <1-16>;

iMAG Response: None.

Description:

Sets the format of the data packets in high-speed data acquisition. A packet can contain 1 to 16 samples (2-32 bytes). The default is 16. Setting SRATE to a value less than 16 will lower the overall composite acquisition rate.

Related Commands:

QTBIASP?, STBIASN, QTBIASN?

STBIASN

Format: STBIASN <CHANNEL 1-3>, <0-100 =%>;

iMAG Response: None.

Description:

Sets the manual tune negative bias percentage level for the specified Flux-Locked Loop channel. The default is 0.

Related Commands:

QTBIASN?, STBIASP, QTBIASP?

STBIASP

Format: STBIASP <CHANNEL 1-3>, <0-100 =%>;

iMAG Response: None.

Description:

Sets the manual tune positive bias percentage level for the specified Flux- Locked Loop channel value (Applies to Flux-Locked Loop “-H” configuration, designed for use with HTS sensors). The default is 0.

Related Commands:

QTBIASP?, STBIASN, QTBIASN?

STMOD

Format: STMOD <CHANNEL 1-3>, <0-100 =%>;

iMAG Response: None.

Description:

Sets the manual tune modulation percentage level for the specified Flux Locked Loop channel. The default is 0.

Related Commands:

QTMOD?

STSKEW

Format: STSKEW <CHANNEL 1-3>, <-0-100 =%>;

iMAG Response: None.

Description:

Sets the manual tune skew level percentage for the specified Flux Locked Loop channel value (Applies to Flux Lock Loop “-H” configuration, designed for use with HTS sensors). The default is 0.

Related Commands:

QTSKEW?

SYSCHAN

Format: SYSCHAN <Channel 1-3>, <for 1-3, 0=OFF, 1=LTS, 2=HTS,
for 4(Aux)0=OFF, 1=ON>;

iMAG Response: None

Description:

Configures the 4 system channels. Channels 1-3 can be set to LTS, HTS or Disabled. Channel 4 (aux) can be set to ON or OFF. The default is LTS for channel 1, OFF for the other channels.

Related Commands:

QSYSPARAM?

SYSHEAT

Format: SYSHEAT <1-50 = Heater Activation Time>;

iMAG Response: None.

Description:

Sets the system heater activation time constant from 1 to 50 seconds. The default is 10.

Related Commands:

QSYSPARAM?

SYSVOLT

Format: SYSTVOLT <0-4.5 = Tune Voltage>;

iMAG Response: None

Description:

Sets the system successful tune voltage value. The default is 2.0.

Related Commands:

QSYSPARAM?

SYSWAIT

Format: SYSWAIT <1-50 = Wait After Heater>;

iMAG Response: None

Description:

Sets the system wait time after heater activation. The default is 12.

Related Commands:

QSYSPARAM?

SUERREG

Format: SUERREG<1=Command Error Register, 2=Execution Error Register>, <Register value(decimal)>;

iMAG Response: None.

Description:

Sets the User Error Register enable bits. The register value is converted from decimal to binary and the appropriate register bits are set. User Error registers are internal iMAG registers. The bits are normally set to zero. If an error condition occurs, and the enable bit for that condition is set, the specific GPIB Standard Event Status Register bits are set accordingly (bit 5 of ESR for command, bit 4 of ESR for Execution).

Command Error Register Bit Definition:

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Not Used	Not Used	Not Used	Not Used	Not Used	Bad Parameter	Unterminated Command	Unknown Command

Execution Error Register Bit Definition:

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Not Used	Not Used	Not Used	Transmit Buffer Overflow	Parity Error	Unknown GPIB Error	Receive Buffer Overflow	Transmit Buffer Under flow

Related Commands:

QUERREG?

Appendix B

IEEE 488.2 and RS-232 Example Programs

Appendix B: Example Programs

Introduction

The iMAG may be controlled remotely using either the RS-232 or GPIB (IEEE-488) protocol. All of the functions available on the front panel are also available via remote interface. This allows you to write simple programs to control your iMAG, or even create an instrument driver. You can also perform high-speed data acquisition using GPIB protocol. Voltage samples can be acquired from all four channels at a composite rate of up to 20,000 samples per second.

To control your iMAG using a computer you will need the following:

RS232: 1) RS-232 cable

GPIB: 1) GPIB cable and 1) National Instruments GPIB (IEEE-488) card or equivalent. For high-speed data acquisition applications with GPIB, we recommend using at least an IBM PC compatible computer with a 486 33 MHz processor, a Macintosh Computer with either a 68040 or Power PC processor, or equivalent processing power.

DISCLAIMER

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GPIB Notes

The following table illustrates the GPIB configuration “GPIB0” accessed by executing the National Instruments program “ibconf”.

GPIB Primary Address -----	0
Secondary GPIB Address -----	NONE
Terminate Read on EOS -----	NO
Set EOI with EOS on Writes -----	NO
Type of compare on EOS -----	7-bit
EOS byte -----	00h
Send EOI at end of Write -----	No
System Controller -----	Yes
Assert REN when SC -----	No
Enable Auto Serial Polling -----	No
Enable CIC Protocol -----	No
Bus Timing -----	350 nsec
Cable Length for High Speed -----	Off
Parallel Poll Duration -----	Default
Use GPIB interface -----	Yes
Base I/O Address -----	02C0h
Interrupt Level -----	11
DMA channel -----	5
DMA Transfer Mode -----	Demand

The following table illustrates the GPIB configuration “dev15” accessed by executing the program National Instruments program “ibconf”. In this case the iMC-303 Multichannel SQUID Controller is configured with GPIB address 15, which is the default address.

Primary GPIB Address -----	15
Secondary GPIB Address -----	None
Timeout setting -----	3 sec
Serial Poll Timeout -----	1 sec
Terminate Read on EOS -----	Yes
Set EOI with EOS on Writes -----	No
Type of compare on EOS -----	7-bit
EOS byte -----	0Ah
Send EOI at end of Write -----	No
Enable Repeat Addressing -----	No

RS-232 Example Program

The following is a sample "C" language DOS program written for the iMC-303 Controller.

TEST1.C is a simple test program which verifies the communications link between the iMC-303 Controller and the host computer.

```
/* TEST1.c - A simple RS232 test program for the iMC-303 using National Instruments RS232 library */
```

```
#define COM1 1
#include "rs232.h"
#include <stdio.h>
#include <string.h>
char inbuf[80];
int i;

void main(void)
{
    OpenComConfig(COM1,9600,0,8,1,80,80,0,0);    /* initialize com1 */
    ComWrt(COM1,"*IDN?;",6);                    /* send command */
    for(i=0;i<10000;i++) i=i*i;                /* delay loop */
    ComRd(COM1,inbuf,35);                       /* read response */
    inbuf[strlen(inbuf)] = '\0';                /* null terminate string */
    printf("Connected to: %s \n",inbuf);
} /* end of TEST1.C */
```

GPIB Example Programs

The following are sample "C" language DOS programs written for the iMC-303 Controller.

TEST2.C is a simple program which verifies the communications link between the iMC-303 Controller and the host computer.

/ TEST2.c - A simple GPIB test program for the iMC-303 using National Instruments GPIB library */*

```
#include "decl.h"           /* DOS GPIB header file */
#include <stdio.h>
#include <string.h>
int handle;
char inbuf[80];
int i;

void main(void)
{
    handle = ibfind("DEV15");      /* connect to device */
    if ( handle < 0 )
    {
        printf("error - no connection established");
        return;
    }
    ibtmo(handle,11);             /* set timeout to 1 seconds */
    ibwrt(handle,"*IDN?;",6);     /* query device ident. */
    for(i=0;i<10000;i++) i=i*i;   /* delay loop */
    ibrd(handle,inbuf,80);       /* read response */
    inbuf[strlen(inbuf)] = '\0';  /* null terminate string */
    printf("Connected to: %s \n",inbuf);
} /* end of TEST2.C */
```

TEST3.C is a model program that verifies the communications link between the iMC-303 Controller and the host computer through a series of basic commands found in the iMAG command set. This program can be used as a foundation on which more sophisticated programs can be built.

/ TEST3.C - a better GPIB test program for the iMC-303 using National Instruments GPIB library */*

```
#include "decl.h"           /* DOS gpib header file */
#include <stdio.h>
#include <string.h>
void write_gpib(char *send);
void wait_loop(long num);
void query_gpib(char *send, char *rcvd);
int HANDLE;

void main(void)
{
    char inbuf[80];
    int tuning;

    HANDLE = ibfind("DEV15");    /* connect to device    */
    if ( HANDLE < 0 )
    {
        printf("error - no connection established");
        return;
    }
    ibeos(HANDLE,0x140A);        /* EOS on linefeed    */
    ibtmo(HANDLE,12);           /* 3 second timeout   */
    write_gpib("CLS");          /* reset buffers       */
    wait_loop(6);
    query_gpib("IDN?;",inbuf);   /* get device id       */
    printf("Connected to %s \n",inbuf);
    write_gpib("SISTATE1;");     /* set to run mode     */
    query_gpib("QSAMP?1;",inbuf); /* read ch1 voltage    */
    printf("channel 1 reading : %s \n",inbuf);
    write_gpib("SYSCHAN2,1;");   /* enable channel 2    */
    write_gpib("SDPCHAN2;");     /* set display to ch2  */
    query_gpib("QSAMP?2;",inbuf); /* read ch2 voltage    */
    printf("channel 2 reading : %s \n",inbuf);
    query_gpib("QHPF?1;",inbuf); /* query ch1 HP filter */
    printf("channel 1 HP filter: %s \n",inbuf);
    query_gpib("QGAIN?2;",inbuf); /* query ch2 gain      */
    printf("channel 2 gain: %s \n",inbuf);

    printf("now starting auto tune \n");
    write_gpib("SISTATE3;");
    tuning = 1;
    while ( tuning )
    {
        /* start auto-tune */
        printf(".");
        query_gpib("QISTATE?;",inbuf); /* loop until done */
        if ( strcmp(" 3;",inbuf) != 0 )
            tuning = 0;
        wait_loop(12);
    }
}
```

```
    query_gpib("QTUNESTAT?;",inbuf);    /* get tune results    */
    printf("\nresults of auto-tune: %s\n",inbuf)
} /* end main */
```

```
/* a routine to send a command to the iMC-303 */
```

```
void write_gpib(char *send)
{
    ibwrt(HANDLE,send,strlen(send));
    if ( ibsta & 0x8000 )                /* check for GPIB error */
        printf("GPIB error %d on ibwrt\n",iberr);
} /* end write_gpib */
```

```
/* a delay loop */
```

```
void wait_loop(long num)
{
    long i, j=0;

    for ( i=0; i<num*10000; i++ )
        j = 2 * j;
} /* end wait_loop */
```

```
/* a routine to send a query to the iMC-303, and read the response */
```

```
void query_gpib(char *send, char *recv)
{
    char buffer[80];

    write_gpib(send);                /* send command    */
    wait_loop(5);                    /* wait for response    */
    ibrd(HANDLE,buffer,80);          /* read response    */
    if ( ibsta & 0x8000 )            /* check for GPIB error    */
    {
        printf("GPIB error %d on ibrd\n",iberr);
        return;
    }
    buffer[ibcnt-1] = '\0';          /* null terminate string */
    strcpy(recv,buffer);
} /* end query_gpib */
```

TEST4.C is a test program that verifies the Data Acquisition function of the iMC-303 Controller. The Data Acquisition is initialized and assigned a 1000 byte buffer, then the iMC-303 acquires 1000 bytes of data from each initialized channel.

```
/* TEST4.C - get a buffer of data using high-speed data acquisition, and National Instruments GPIB library */
```

```
#include "decl.h"                /* DOS gpib header file */
#include <stdio.h>
#include <string.h>

void write_gpib(char *send);
void wait_loop(long num);
int HANDLE;

void main(void)
{
    char inbuf[1000];

    HANDLE = ibfind("DEV15");    /* connect to iMAG          */
    ibtmo(HANDLE,12);           /* set timeout to 3 sec     */
    ibeos(HANDLE,0x0);          /* turn off EOS             */
    write_gpib("SDACQ1,3;");    /* channel 1, 20 kHz        */
    write_gpib("SARM;");        /* trigger data flow        */
    wait_loop(10);
    ibrd(HANDLE,inbuf,1000);    /* read 1000 bytes          */
    printf("read %d bytes from iMAG \n",ibcnt);
    write_gpib("SDARM;");       /* stop data flow           */
    write_gpib("CLS;");         /* clear iMAG out buffer    */
}
```

See Appendix C for more information on high speed data acquisition.

Appendix C

High Speed Data Acquisition Notes

Appendix C: Application Notes on High Speed Data Acquisition

The iMC-303 Multichannel SQUID Controller is designed to make high speed data acquisition simple and reliable. Data may be acquired at a composite rate of up to 20,000 samples per second via the IEEE-488 bus, and you can sample 1, 2, or 4 channels simultaneously. There is no limit to the number of samples you can acquire. For large acquisitions, a synchronization signal is provided to ensure integrity.

To acquire voltage samples from the iMC-303, you will need a National Instruments IEEE 488.2 GPIB card or equivalent, a GPIB cable, and an IBM PC compatible with at least a 486-33 MHz processor, or equivalent processing power.

iMAG and IEEE-488 commands

In this document, iMAG commands will use the following font: ***iMAG***, and IEEE-488(GPIB) functions will use: **GPIB**.

There are 8 data acquisition commands for the iMAG. They are defined as follows:

SARM: Triggers the flow of data from the iMAG across the GPIB interface.
SDARM: Halts the flow of data from the iMAG.
SDACQ: Selects the channel(s) to sample, and the data acquisition rate.
QDACQ: Query the iMAG for the data acquisition parameters.
SDAPCK: Set how often the SRQ line is set during high-speed acquisition.
QDAPCK: Queries how often the SRQ line is set during high-speed acquisition.
SRATE: Set up the format of the data packets for high-speed data acquisition

Some of the National Instruments **GPIB** functions that can also be used are:

IBFIND: makes a GPIB connection.
IBTMO: sets the timeout period for a read.
IBRD: reads characters from the iMAG.
IBWRT: sends a command to the iMAG.
IBRSP: performs a serial poll.

Acquiring Data

The first step in acquiring data is making sure you have a working GPIB connection between your PC and the iMC-303 Multichannel SQUID Controller. Appendix B contains several test programs that may be helpful. It should be noted that RS232 cannot be used for high-speed acquisition. Once your connection is established, the next step is to enable the SQUID channels you want to acquire from. **SYSCHAN** is used to enable the appropriate channels. Next, set the iMC-303's data acquisition parameters. **SDACQ** allows you to select the channel or channels that will be sampled, and also select the data acquisition rate. If one of the channels you specify is not enabled, the **SDACQ** command will not be accepted. See Appendix A for valid configurations.

To trigger the flow of data, use the **SARM** command. When **SARM** is received, the iMC-303 front panel display will indicate that a high-speed transfer is in progress, and data will be sent across the GPIB interface.

IBRD or **IBRDA** can be used to read the data into a character buffer. **IBTMO** should be used to set the time-out limit for **IBRD**. If the time-out period is too short, **IBRD** will terminate before it has acquired all of the bytes you requested. The size of the buffer can be as large as your computer will allow, up to 1 gigabyte. If you

need to acquire data over a long period of time, you can read smaller buffers in a loop. See the Synchronization section below.

When you have acquired all the data desired, issue the **SDARM** command to stop the flow of data. Since there is a small lag time between sending the **SDARM** command and the time that the flow of data actually stops, there may be a few bytes of data remaining in the iMC-303's output buffer. Use ***CLS** to clear out the buffer.

Data Format

In high-speed data acquisition mode, the iMC-303 Multichannel SQUID Controller sends out 2 byte ADC integer values from the selected channels. To scale convert the 2 byte ADC integer value to a floating point voltage sample, multiply by 4.5/32768.0. The following "C" routine shows how to convert a sample of binary data using an IBM PC.

```
void char_to_float(char *cval, float *fval)
{
    union f_num
    {
        char cval[2];
        short ival;
    } fnum;

    fnum.cval[0] = cval[1];
    fnum.cval[1] = cval[0];
    *fval = fnum.ival*4.5/32768.0;
}
```

Since the data is sent as individual bytes, it must be pieced back together into meaningful data. In the above routine, a union is used to combine two individual character bytes into a single 2 byte short integer. Notice that the two bytes must be swapped. Finally, the short is converted to floating point.

The 2 byte samples are sent across the remote interface in packets. By default there are 16 samples (32 bytes) in each packet. The **SRATE** command sets the number of samples in each packet. An SRATE value of 1-16 will set the number of samples in each packet to 1-16 respectively. It should be noted that setting the SRATE to less than 16 will reduce the composite rate of transfer, since fewer samples are being sent.

If more than one channel is selected, the samples will be interleaved. For example, if you are sampling channels 1 and 3, the stream of data will look like this:

byte 1	byte 2	byte 1	byte 2	byte 1	byte 2	byte 1	byte 2
channel 1		channel 3		channel 1		channel 3	

Synchronization

IBRD allows reading a buffer of up to 1 gigabyte, provided the computer has that much available memory. If the computer does not have sufficient space to store all the data you wish to acquire, the computer can acquire smaller buffers in a loop, and process the data in between reads. When acquiring data in a loop over a long period of time, it is advisable to use synchronization to ensure the integrity of the data.

To achieve synchronization, the iMC-303 Controller asserts the SRQ (service request) periodically. By default, the SRQ line is always asserted once after 100 packets are sent. The **SDAPCK** command can be used to change how often the SRQ line is set. The frequency of the SRQ can be set from once after each packet, to once after every 400 packets. This allows you to use a serial poll to test for the SRQ line, and then read a buffer of data when the line is asserted. The following "C" code fragment shows a typical coding scheme using SRQ.

```
ibwrt(handle,"*SRE 255;",9);          /* enable status register */
ibwrt(handle,"SDACQ1,0;",9);         /* channel 1, 2500 kHz */
ibwrt(handle,"SDAPCK100;",10);      /* set SRQ freq to 100 */
ibwrt(handle,"SARM;",5);           /* start data flow */
count = 0;
while ( count < bytes )             /* while bytes to acquire */
{                                     /* is less than the count */
    statbyte = 0;
    while ( !(statbyte & 0x40) )     /* serial poll device until */
        ibrsp(TC_handle, &statbyte); /* SRQ line is set */
    ibrd(TC_handle,inbuf,3200);      /* read buffer of data */
    /* process data here */          /* process and write to file */
    count += ibcntl;                 /* add bytes read to count */
}
ibwrt(handle,"SDARM;",6);           /* disarm data flow */
```

Further Information

For more detailed information on iMAG commands, see Appendix A. Appendix B provides some sample “C” language programs to help you get started. For information on GPIB (IEEE-488) products and software, please contact National Instruments directly.

Appendix D

SQUID Interface Connector Pinout

Appendix D: SQUID Interface Connector Pinout

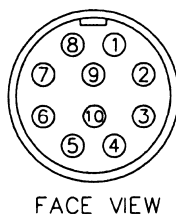


Figure 18 iFL-301 Pigtail Connector Pinout (Face View)

Pinout	Description
1	HEAT+
2	SIGNAL+
3	SIGNAL-
4	HEAT-
5	FEEDBACK-
6	FEEDBACK+
7	MOD+
8	BIAS+
9	BIAS-
10	MOD-

Table 6 iFL-301 Pigtail Connector Pinout (Face View)

Note: The connector shell, twisted pair shields, and cable shield are grounded to the connector shell and a circuit board ground.

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